

# LECTURE 13

## CONDITION NUMBER

Measures the sensitivity of a problem to perturbations (for instance to rounding errors)

$$f: V \rightarrow W$$

$f$  is a function from a vector space  $V$  to another vector space  $W$ .

## EXAMPLES

① Consider

$$p_\epsilon(x) = x^2 - \epsilon$$

Positive root as a function of  $\epsilon$

$$r_+(\epsilon): \mathbb{R} \rightarrow \mathbb{C}$$

$$r_+(\epsilon) = \sqrt{\epsilon}$$

②

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$f(x) = x_1^2 - x_2^2$$

③ Given  $A \in \mathbb{C}^{n \times n}$  and  $b \in \mathbb{C}^n$ .  
Consider the linear system

$$Ax = b$$

The solution  $x$  as a function of  $A$ .

$$x: \mathbb{C}^{n \times n} \rightarrow \mathbb{C}^n \quad (\text{assume } b \text{ is fixed})$$

$$x(A) = A^{-1}b \quad (\text{assuming } A \text{ is invertible})$$

④ Least squares problem

Given  $A \in \mathbb{C}^{m \times n}$  (with  $m > n$ )

and  $b \in \mathbb{C}^m$ . Find  $\hat{x}$  so that

$$\|A\hat{x} - b\|_2$$

is as small as possible.

The solution  $\hat{x}$  as a function of  $b$

$$\hat{x}: \mathbb{C}^m \rightarrow \mathbb{C}^n$$

$$\hat{x}(b) = (A^*A)^{-1}A^*b \quad (\text{assuming } \text{rank}(A) = n; \text{ follows from the normal eqn})$$

②

## Sensitivity of $f$

How does  $f$  change w.r.t. changes in the input?

## Absolute Condition Number

Measure of sensitivity of  $f(x)$

$$K = \lim_{\delta \rightarrow 0} \sup_{\|\delta x\| \leq \delta} \frac{\|f(x+\delta x) - f(x)\|}{\|\delta x\|} \quad \delta_f$$

## EXAMPLE

Positive root of  $p_\epsilon(x) = x^2 - \epsilon$   
as a function of  $\epsilon$  at  $\epsilon = 0$

$$\frac{|\underbrace{r_+(\delta\epsilon) - r_+(0)}_{\delta r_+}|}{|\delta\epsilon|} = \frac{|\sqrt{\delta\epsilon} - 0|}{|\delta\epsilon|}$$

$$= \frac{1}{\sqrt{\delta\epsilon}}$$

$$K = \lim_{\delta \rightarrow 0} \sup_{|\delta\epsilon| \leq \delta} \frac{1}{\sqrt{\delta\epsilon}}$$

$$= \infty$$

Root-finding problem in general is ill-conditioned.

## TERMINOLOGY

ill-conditioned : condition number is large

well-conditioned : condition number is small

## REMINDER

$\sup S$  : supremum (smallest upper bound) of the set  $S$ .

e.g.

$$\therefore \sup \left\{ \frac{1}{n} : n > 1 \right\} = 1$$

$$\sup \left\{ \frac{x^2 - 1}{2x^2} : x \neq 0 \right\} = \frac{1}{2}$$

## Jacobian of a multi-variate function

$$f : \mathbb{C}^n \rightarrow \mathbb{C}^m$$

$$\boxed{\text{Jacobian of } f \text{ at } x} \quad J(x) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \dots & \frac{\partial f_m}{\partial x_n} \end{bmatrix} \quad \left( \begin{array}{l} \text{matrix} \\ \text{of partial} \\ \text{derivatives} \end{array} \right) \quad m \times n$$

## EXAMPLES

$$\textcircled{1} \quad f(x) = x_1^2 - x_2^2$$

$$J(x) = \begin{bmatrix} 2x_1 & -2x_2 \end{bmatrix}$$

$$\textcircled{2} \quad f(x) = \begin{bmatrix} x_1^2 - x_2^2 \\ x_1 x_2 \end{bmatrix}$$

$$J(x) = \begin{bmatrix} 2x_1 & -2x_2 \\ x_2 & x_1 \end{bmatrix}$$

## REMARK

Suppose  $f: \mathbb{C}^n \rightarrow \mathbb{C}$

$$J(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \dots & \frac{\partial f}{\partial x_n} \end{bmatrix}$$
$$= \nabla f(x)^T$$

where  $\nabla f(x)$  is the gradient vector

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

## Absolute condition number in terms of Jacobian

Suppose  $f: \mathbb{C}^n \rightarrow \mathbb{C}^m$  is twice differentiable. Then (by Taylor's thm; we will see this in detail next semester)

$$(*) \quad f(x + \delta x) = f(x) + J(x) \delta x + O(\|\delta x\|^2)$$

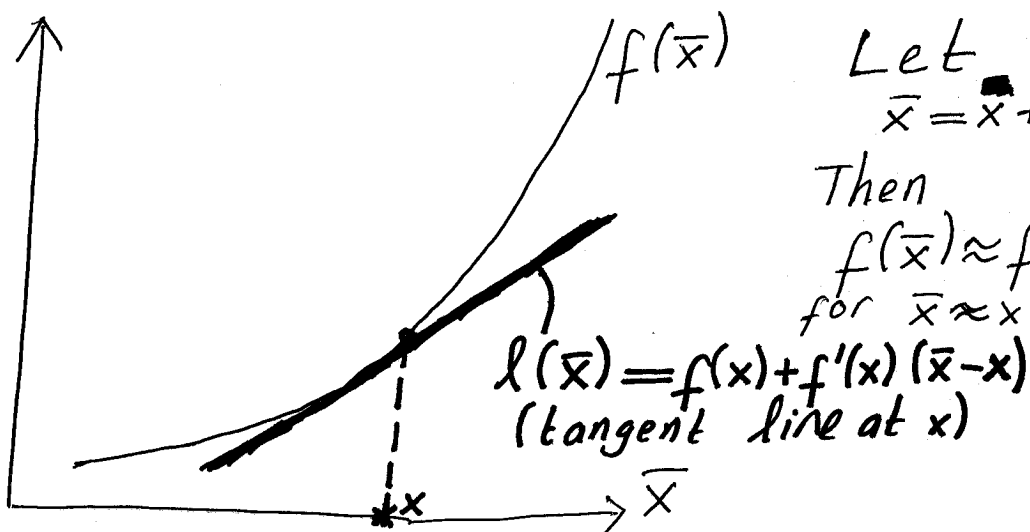
### REMARKS

(1) We are interested in  $\delta x$  small in norm.  $O(\|\delta x\|^2)$  represents terms proportional to  $\|\delta x\|^2$  or smaller (e.g.  $2\|\delta x\|^2 + \|\delta x\|^3$ ); This is the usual big-O notation, but we take the limit as  $\delta x \rightarrow 0$ .  $g(\delta x) = O(f(\delta x))$  means  $cf(\delta x)$  dominates  $g(\delta x)$  as  $\delta x \rightarrow 0$  for some constant  $c$ .

(2) Suppose  $f: \mathbb{R} \rightarrow \mathbb{R}$  is differentiable. Then

$$f(x + \delta x) \approx f(x) + f'(x) \delta x$$

is the linear (tangent line) approximation at  $x$ .



More generally when  $f: \mathbb{C}^n \rightarrow \mathbb{C}^m$   
 $f(x+\delta x) \approx f(x) + J(x)\delta x$   
 is the linear approximation at  $x$ .

Using (\*)

$$\begin{aligned}
 K &= \lim_{\delta \rightarrow 0} \sup_{\|\delta x\| \leq \delta} \frac{\|f(x+\delta x) - f(x)\|}{\|\delta x\|} \\
 &= \lim_{\delta \rightarrow 0} \sup_{\|\delta x\| \leq \delta} \frac{\|f(x) + J(x)\delta x + O(\|\delta x\|^2) - f(x)\|}{\|\delta x\|} \\
 &= \lim_{\delta \rightarrow 0} \sup_{\|\delta x\| \leq \delta} \frac{\|J(x)\delta x\| + O(\|\delta x\|)}{\|\delta x\|} \\
 &= \lim_{\delta \rightarrow 0} \|J(x)\| = \|J(x)\|
 \end{aligned}$$

vector induced matrix norm

### SUMMARY

For  $f: \mathbb{C}^n \rightarrow \mathbb{C}^m$  twice differentiable  
 $K = \|J(x)\|$

### EXAMPLE

For  $f(x) = x_1^2 - x_2^2$  using the 2-norm

$$K = \|[2x_1 \quad -2x_2]\|_2 = 2\|x\|_2$$

## Relaxed absolute condition number

For  $\delta > 0$  small in absolute value

$$K_\delta = \sup_{\|\delta x\| \leq \delta} \frac{\|f(x + \delta x) - f(x)\|}{\|\delta x\|}$$

For small  $\delta$

$$K \approx K_\delta$$

We will often depend on  $K_\delta$  rather than  $K$  in our accuracy analyses.

### EXAMPLE

Matrix-vector product as a function of matrix

$$f: \mathbb{C}^{n \times n} \rightarrow \mathbb{C}^n$$

$$f(A) = Ax \quad (x \text{ is fixed})$$

Then

$$K_\delta = \sup_{\|\delta A\| \leq \delta} \frac{\|f(A + \delta A) - f(A)\|}{\|\delta A\|}$$

$$= \sup_{\|\delta A\| \leq \delta} \frac{\|(A + \delta A)x - Ax\|}{\|\delta A\|}$$

$$= \sup_{\|\delta A\| \leq \delta} \frac{\|\delta Ax\|}{\|\delta A\|}$$



$$= \sup_{\|\delta A\| \leq \delta} \frac{\|\delta A\| \|x\|}{\|\delta A\|} = \|x\|$$

Choose  $\delta A$  s.t.

$$\|\delta A x\| = \|\delta A\| \|x\|$$

Indeed

$$\kappa = \lim_{\delta \rightarrow 0} \kappa_{\delta} = \|x\|$$

Relative condition number

$$\begin{aligned} \tilde{\kappa} &= \lim_{\delta \rightarrow 0} \sup_{\|\delta x\| \leq \delta} \frac{\|f(x+\delta x) - f(x)\| / \|f(x)\|}{\|\delta x\| / \|x\|} \\ &= \frac{\kappa \|x\|}{\|f(x)\|} \end{aligned}$$

Relative condition number is used more often than the absolute condition number in practice. This is due to fact that IEEE standards introduce constant relative errors (proportional to  $\epsilon_{mach}$ ).

EXAMPLE

For  $f(x) = x_1^2 - x_2^2$  using the 2-norm

$$\tilde{\kappa} = \frac{\| [2x_1 \quad -2x_2] \|_2 \|x\|_2}{|x_1^2 - x_2^2|}$$

(9)

$$\tilde{\kappa} = 2 \|x\|_2^2 / |x_1^2 - x_2^2|$$

$\tilde{\kappa}$  is large (problem is ill-conditioned) if  $x_1 \approx x_2$ .

For  $f: \mathbb{C}^n \rightarrow \mathbb{C}^m$  twice-differentiable

$$\tilde{\kappa} = \frac{\|J(x)\| \|x\|}{\|f(x)\|}$$

Relaxed relative condition number

$$\begin{aligned} \tilde{\kappa}_\delta &= \sup_{\|\delta x\| \leq \delta} \frac{\|f(x+\delta x) - f(x)\| / \|f(x)\|}{\|\delta x\| / \|x\|} \\ &= \frac{\kappa_\delta \|x\|}{\|f(x)\|} \end{aligned}$$

where  $\delta > 0$  (supposed to be small in absolute value)

For small  $\delta > 0$

$$\tilde{\kappa} \approx \tilde{\kappa}_\delta$$

## EXAMPLE

For the matrix-vector product example  
with

$$f(A) = Ax$$

we have

$$\tilde{\kappa}_\delta = \frac{\kappa_\delta \|A\|}{\|f(A)\|} = \frac{\|x\| \|A\|}{\|Ax\|}$$

Notice that (assuming  $A$  is invertible)

$$\|x\| = \|A^{-1}Ax\| \leq \|A^{-1}\| \|Ax\|$$

$$\implies \frac{\|x\|}{\|Ax\|} \leq \|A^{-1}\|$$

Therefore

$$\tilde{\kappa}_\delta \leq \|A^{-1}\| \|A\|$$

and

$$\tilde{\kappa}_\bullet = \lim_{\delta \rightarrow 0} \tilde{\kappa}_\delta \leq \|A^{-1}\| \|A\|$$

## Condition number of a matrix

The quantity

$$\kappa(A) = \|A\| \|A^{-1}\|$$

occurs so often in accuracy analyses that it is called the condition number of A.

### EXAMPLE

Let

$$A = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$$

and

$$A^{-1} = \begin{bmatrix} 1/3 & 0 \\ 0 & 1 \end{bmatrix}$$

Condition number of A w.r.t. the 2-norm

$$\begin{aligned} \kappa(A) &= \|A\|_2 \|A^{-1}\|_2 \\ &= 3 \cdot 1 = \underline{\underline{3}} \end{aligned}$$

## Condition number of a matrix w.r.t. 2-norm

Let

$$A = U \Sigma V^*$$

be an SVD of  $A \in \mathbb{C}^{n \times n}$ .

Then an SVD for  $A^{-1}$  is given by

$$\begin{aligned} A^{-1} &= (V^*)^{-1} \Sigma^{-1} U^{-1} \\ &= V \Sigma^{-1} U^* \end{aligned}$$

In particular suppose

$$\Sigma = \begin{bmatrix} \sigma_1 & & & 0 \\ & \sigma_2 & & \\ & & \dots & \\ 0 & & & \sigma_n \end{bmatrix} \quad \left( \begin{array}{l} \text{where} \\ \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \end{array} \right)$$

meaning

$$\Sigma^{-1} = \begin{bmatrix} 1/\sigma_1 & & & 0 \\ & 1/\sigma_2 & & \\ & & \dots & \\ 0 & & & 1/\sigma_n \end{bmatrix} \implies \begin{aligned} \|A^{-1}\|_2 &= \|\Sigma^{-1}\|_2 \\ &= 1/\sigma_n \end{aligned}$$

Condition number of  $A$  in terms of singular values

$$\kappa(A) = \|A\|_2 \|A^{-1}\|_2 = \frac{\sigma_1}{\sigma_n}$$