

LECTURE 22SIMILARITY TRANSFORMATIONS

Let $A \in \mathbb{C}^{n \times n}$,

$S \in \mathbb{C}^{n \times n}$ be invertible.

The transformation

$$T: A \rightarrow S^{-1}AS$$

is called a similarity transformation.

The matrices A and $S^{-1}AS$ are said to be similar.

EXAMPLE

Consider the similarity transformation

$$\begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix}$$

\rightarrow

$$\begin{bmatrix} -2 & 2 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} -2 & 2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} -3 & 0 \\ 0 & 1 \end{bmatrix}$$

The matrices

$$\begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} -3 & 0 \\ 0 & 1 \end{bmatrix}$$

are similar with the same eigenvalues $\lambda_1 = -3$ and $\lambda_2 = 1$.

THM (Similarity Transformation & Eigenvalues)

Suppose $A, B \in \mathbb{C}^{n \times n}$ are similar matrices. Then A and B have exactly the same set of eigenvalues with the same algebraic and geometric multiplicities.

PROOF

There exists an S (invertible) such that

$$B = S^{-1}AS.$$

But then

$$\begin{aligned} \det(B - \lambda I) &= \det(S^{-1}AS - \lambda I) \\ &= \det(S^{-1}AS - \lambda S^{-1}S) \end{aligned} \quad (2)$$

$$= \det(S^{-1}(A - \lambda I)S)$$

$$= \underbrace{\det(S^{-1})}_{\neq 0} \det(A - \lambda I) \underbrace{\det(S)}_{\neq 0}$$

Therefore

$$\det(A - \lambda I) = 0 \iff \det(B - \lambda I) = 0.$$

In other words A and B have the same characteristic polynomial meaning they share the same eigenvalues with same algebraic multiplicities.

Furthermore since S is invertible,

$$\begin{aligned} \text{rank}(A - \lambda I) &= \text{rank}(S^{-1}(A - \lambda I)S) \\ &= \text{rank}(B - \lambda I) \end{aligned}$$

$$\implies \dim(\text{Null}(A - \lambda I)) = \dim(\text{Null}(B - \lambda I)).$$

Consequently eigenvalues of A and B have the same geometric multiplicities. \square

EXAMPLE (Algebraic & Geometric Multiplicities)

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

- * $\lambda = 1$ is the only eigenvalue.
- * $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $v_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ are associated eigenvectors.
- * $E_\lambda = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} = \mathbb{R}^2$ (eigenspace associated with $\lambda=1$)
- * algebraic multiplicity of $\lambda=1$ is 2.
- * geometric multiplicity of $\lambda=1$ is 2.

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- * $\lambda = 1$ is the only eigenvalue.
- * $E_\lambda = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$
- * algebraic multiplicity of $\lambda=1$ is 2.
- * geometric multiplicity of $\lambda=1$ is 1.

THM (Algebraic & Geometric Multiplicities)

Let $A \in \mathbb{C}^{n \times n}$ and $\lambda \in \mathbb{C}$ be an eigenvalue of A . Then

algebraic multip. of λ

\geq
geometric multip. of λ

PROOF

Let $\{q_1, q_2, \dots, q_m\}$ be an orthonormal basis for $E_\lambda = \text{Null}(A - \lambda I)$.

Form an unitary matrix of the form

$$Q = \underbrace{\begin{bmatrix} q_1 & q_2 & \dots & q_m \end{bmatrix}}_{Q_m} \underbrace{\begin{bmatrix} q_{m+1} & \dots & q_n \end{bmatrix}}_{\hat{Q}}.$$

Now A is similar to

$$Q^* A Q = \begin{bmatrix} Q_m^* \\ \hat{Q}^* \end{bmatrix} A \begin{bmatrix} Q_m & \hat{Q} \end{bmatrix}$$

$$= \begin{bmatrix} \lambda Q_m^* Q_m & Q_m^* A \hat{Q} \\ \lambda \hat{Q}^* Q_m & \hat{Q}^* A \hat{Q} \end{bmatrix}$$

⑤

$$= \begin{bmatrix} \lambda I_m & Q_m^* A \hat{Q} \\ 0 & \hat{Q}^* A \hat{Q} \end{bmatrix}$$

Consequently the algebraic multiplicity of λ as an eigenvalue of $Q^* A Q$ and A is at least $m = \dim(E_\lambda)$.

□

TERMINOLOGY

An eigenvalue λ is called

* defective if its algebraic multiplicity is strictly greater than its geometric multiplicity,

* simple if its algebraic multiplicity is one,

* (or non-defective) semi-simple if its algebraic multiplicity is equal to its geometric multiplicity.

A matrix $A \in \mathbb{C}^{n \times n}$ is called non-defective if

* it has n linearly independent eigenvectors, equivalently

* all eigenvalues of A are semi-simple (note that eigenvectors associated with different eigenvalues are linearly independent.) (6)

EXAMPLE

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

is defective, because it has only one linearly independent eigenvector lying in $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$.

* This is due to the fact that the eigenvalue $\lambda=1$ is defective.

$$\begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix}$$

is non-defective, because it has two linearly independent eigenvectors

$v_1 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ associated with eigenvalues $\lambda_1 = -3$ and $\lambda_2 = 1$, respectively.

* This is due to the fact that both eigenvalues are simple (therefore semi-simple).

In general given a non-defective matrix $A \in \mathbb{C}^{n \times n}$ with

- * the set of linearly independent eigenvectors $\{v_1, v_2, \dots, v_n\}$,
- * and associated eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$.

$$Av_1 = \lambda_1 v_1, \dots, Av_n = \lambda_n v_n$$

$$A \underbrace{[v_1 \dots v_n]}_V \xrightarrow{\implies} \underbrace{[v_1 \dots v_n]}_V \underbrace{\begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}}_\Lambda$$

$$A = \underbrace{V}_{\substack{\text{matrix} \\ \text{of} \\ \text{eigenvecs}}} \underbrace{\Lambda}_{\substack{\text{matrix} \\ \text{of} \\ \text{eigenvals}}} V^{-1}$$

The decomposition

$$A = V \Lambda V^{-1}$$

where $V \in \mathbb{C}^{n \times n}$ is invertible and

$\Lambda \in \mathbb{C}^{n \times n}$ is diagonal is called the eigenvalue (or spectral) decomposition of A. (8)

EXAMPLE

$$\begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} = (-3) \begin{bmatrix} -2 \\ 1 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = (1) \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} -2 & 2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -3 & 0 \\ 0 & 1 \end{bmatrix}$$

eigenvalue decomposition $\begin{bmatrix} -1 & 4 \\ 1 & -1 \end{bmatrix} = \underbrace{\begin{bmatrix} -2 & 2 \\ 1 & 1 \end{bmatrix}}_V \underbrace{\begin{bmatrix} -3 & 0 \\ 0 & 1 \end{bmatrix}}_\Lambda \underbrace{\begin{bmatrix} -2 & 2 \\ 1 & 1 \end{bmatrix}^{-1}}_{V^{-1}}$

DEFN (Diagonalizability)

A matrix $A \in \mathbb{C}^{n \times n}$ is called diagonalizable if it has an eigenvalue decomposition.

THM (Diagonalizable Matrices)

A matrix $A \in \mathbb{C}^{n \times n}$ is diagonalizable if and only if

- (i) it is non-defective, equivalently
- (ii) all of its eigenvalues are semi-simple.

Computation of Eigenvalues (Overview)

Apply similarity transformations
of form

$$\begin{aligned} (+) A &\longrightarrow Q_1^{-1} A Q_1 \longrightarrow Q_2^{-1} Q_1^{-1} A Q_1 Q_2 \\ &\dots \longrightarrow \underbrace{Q_k^{-1} \dots Q_1^{-1} A Q_1 \dots Q_k}_{A_k} \end{aligned}$$

so that

* $\lim_{k \rightarrow \infty} A_k$ is an upper
triangular matrix.

REMARKS

* Eigenvalues of a triangular matrix
are given by its diagonal entries.

e.g.
$$\begin{bmatrix} -1 & 1 & -1 \\ 0 & 3 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

has the characteristic polynomial

$$p(\lambda) = (\lambda+1)(\lambda-3)(\lambda-2)$$

and eigenvalues

$$\lambda_1 = -1, \lambda_2 = 3, \lambda_3 = 2$$

* Reduction into a diagonal matrix by similarity transformations is too ambitious; not all matrices are diagonalizable.

* In (+) Q_k is indeed a unitary matrix so that

$$A_k = Q_k^* \dots Q_1^* A Q_1 \dots Q_k$$

The reduction into a triangular form by unitary similarity transformations is possible due to the existence of a Schur factorization for every matrix $A \in \mathbb{C}^{n \times n}$.

THM (Schur Factorization)

Every matrix $A \in \mathbb{C}^{n \times n}$ has a factorization of the form

$$(++)\ A = QTQ^*$$

where $Q \in \mathbb{C}^{n \times n}$ is unitary and $T \in \mathbb{C}^{n \times n}$ is upper triangular.

e.g.

$$\underbrace{\begin{bmatrix} 4 & 1 \\ -2 & 7 \end{bmatrix}}_A = \underbrace{\left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \right)}_Q \underbrace{\begin{bmatrix} 5 & 3 \\ 0 & 6 \end{bmatrix}}_T \underbrace{\left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \right)}_{Q^T}$$

PROOF OF THM - SCHUR FACTORIZATION

The proof is by induction on the size of the matrix.

Base case ($n=1$)

Any scalar has trivially a Schur factorization.

Inductive case ($n=k > 1$)

As the inductive hypothesis suppose $(k-1) \times (k-1)$ matrices have factorizations of the form $(++)$.

Let λ be an eigenvalue of A and q be a unit eigenvector associated with λ .

Consider a unitary matrix $Q \in \mathbb{C}^{n \times n}$
of form

$$Q = \begin{bmatrix} q & \hat{Q} \end{bmatrix}$$

satisfying

$$Q^* A Q = \begin{bmatrix} q^* \\ \hat{Q}^* \end{bmatrix} \begin{bmatrix} A q & A \hat{Q} \end{bmatrix}$$

$$= \begin{bmatrix} q^* \\ \hat{Q}^* \end{bmatrix} \begin{bmatrix} \lambda q & A \hat{Q} \end{bmatrix}$$

$$= \begin{bmatrix} \lambda q^* q & \overbrace{q^* A \hat{Q}}^B \\ \lambda \hat{Q}^* q & \underbrace{\hat{Q}^* A \hat{Q}}_C \end{bmatrix}$$

$$= \begin{bmatrix} \lambda & B \\ 0 & C \end{bmatrix}$$

By inductive hypothesis $C \in \mathbb{C}^{(k-1) \times (k-1)}$
has a factorization

where $\tilde{Q} \in \mathbb{C}^{(k-1) \times (k-1)}$ is unitary, \tilde{T} is upper
triangular.

refore

$$Q^* A Q = \begin{bmatrix} \lambda & B \\ 0 & \tilde{Q} \tilde{T} \tilde{Q}^* \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & \tilde{Q} \end{bmatrix} \begin{bmatrix} \lambda & B \tilde{Q} \\ 0 & \tilde{T} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & \tilde{Q}^* \end{bmatrix}$$

$$A = \underbrace{Q \begin{bmatrix} 1 & 0 \\ 0 & \tilde{Q} \end{bmatrix}}_{\hat{Q}} \underbrace{\begin{bmatrix} \lambda & B \tilde{Q} \\ 0 & \tilde{T} \end{bmatrix}}_{\hat{T}} \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & \tilde{Q}^* \end{bmatrix}}_{\hat{Q}^*} Q^*$$

where \hat{Q} is unitary, \hat{T} is upper triangular
implying the existence of a factorization of form $(++)$. \square

Now suppose $A \in \mathbb{C}^{n \times n}$ is Hermitian.

$$A^* = A \implies Q T Q^* = Q T^* Q^*$$

$$\implies T = T^*$$

$\implies T=A$ is diagonal with real entries.

For an Hermitian matrix A the Schur factorization becomes an orthogonal eigenvalue decomposition

$$A = Q \Lambda Q^* \quad (\text{equivalently } A Q = Q \Lambda)$$

EXAMPLE

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

* has real eigenvalues $\lambda_1=3$, $\lambda_2=-1$

* and the associated eigenvectors

$v_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $v_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ are orthogonal

THM (Symmetric Eigenvalue Problem)

Let $A \in \mathbb{C}^{n \times n}$ be Hermitian. Then

- (i) the eigenvalues $\lambda_1, \dots, \lambda_n$ of A are real, and
- (ii) there exists a set of associated orthonormal eigenvectors $\{q_1, \dots, q_n\}$.