

Homework Set #4

Due: Tuesday, December 3, 2013.

Please email your matlab codes to our TA (mkuscu@ku.edu.tr).

1. *Quadratic Forms and Hermitian Matrices*

Consider the quadratic form

$$f(\mathbf{x}) = \frac{1}{9}(-2x_1^2 + 7x_2^2 + 4x_3^2 + 4x_1x_2 + 16x_1x_3 + 20x_2x_3). \quad (1)$$

- (a) Find a symmetric matrix \mathbf{A} so that $f(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x}$.
- (b) Diagonalize the quadratic form using the \mathbf{LDL}^T factorization, and determine the inertia of \mathbf{A} .
- (c) Is this a positive definite form?
- (d) Verify the inertia obtained above is correct by computing the eigenvalues of \mathbf{A} .

2. *Matrix Factorization Coding Experience...*

- (a) Write a Matlab function to find Cholesky Factorization of a positive definite matrix.
- (b) Write another Matlab function to obtain QR factorization based on Gram-Schmidt procedure.

3. *Random Vector Generation...*

Write a MATLAB function whose first couple of lines are provided as follows

```
function out=generaterandvec(N,R)
% Generates zero-mean complex Gaussian random vector sequence with the specified
% covariance matrix
% Usage
% out=generaterandvec(N,R)
% Here
% N: Number of vectors to be generated
% R: The specified covariance matrix.
% out: Output matrix containing vector sequence. Assuming R is a pxp matrix
% out would be a pxN matrix
```

in your function only specialized MATLAB functions you can use are *randn* and *size*.
Generate $N = 100000$ random vectors with covariance

$$\mathbf{R} = \begin{bmatrix} 28 & 15 + 9i & 2 + 21i \\ 15 - 9i & 48 & 15 - 11i \\ 2 - 21i & 15 + 11i & 30 \end{bmatrix}. \quad (2)$$

Calculate the sample covariance matrix for the vector sequence generated using the formula

$$\hat{\mathbf{R}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}_n \mathbf{x}_n^* . \quad (3)$$

Can you find $\hat{\mathbf{R}}$ without using loops? Compare $\hat{\mathbf{R}}$ with the true covariance \mathbf{R} , are they close? does your random generator seem to work fine?

4. Let full QR decomposition of $\mathbf{A} \in \mathcal{C}^{m \times n}$ be given by

$$\mathbf{A} = \mathbf{Q}\mathbf{R} \quad (4)$$

where $\mathbf{Q} \in \mathcal{C}^{m \times m}$ and $\mathbf{R} \in \mathcal{C}^{m \times n}$. Show that

$$\sum_{k=1}^m \sum_{l=1}^n |A_{kl}|^2 = \sum_{k=1}^m \sum_{l=1}^n |R_{kl}|^2 \quad (5)$$