

Math 503: Quiz # 3

Fall 2006

- Write your name and Student ID number in the space provided below and sign.

Student's Name:	
ID Number:	
Signature:	

- You have 60 minutes.
- You may use any statement which has been proven in class, except for the cases where you are asked to reproduce the proof of that statement.
- You may ask any question about the quiz within the first 5 minutes. After this time for any question you may want to ask 5 points will be deducted from your grade (You may or may not get an answer to your question(s).)

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Problem 1. Solve the following Sturm-Liouville problem.

$$y'' + \lambda y = 0, \quad y'(-\pi) = 0, \quad y'(\pi) = 0,$$

i.e., find all real values of  $\lambda$  for which a solution exists and determine this solution. (40 points)

Consider the following case:

$$(1) \quad \lambda \in \mathbb{R}^- \Rightarrow \exists \mu \in \mathbb{R}^+, \quad \lambda = -\mu^2 = 1$$

$$y'' - \mu^2 y = 0 \Rightarrow y = c_1 e^{\mu x} + c_2 e^{-\mu x}$$

$$\Rightarrow y' = \mu (c_1 e^{\mu x} - c_2 e^{-\mu x})$$

$$0 = y'(-\pi) = \mu (c_1 e^{-\pi\mu} - c_2 e^{\pi\mu}) \quad \mu \neq 0 \Rightarrow$$

$$0 = y'(\pi) = \mu (c_1 e^{\pi\mu} - c_2 e^{-\pi\mu})$$

$$c_1 = e^{2\pi\mu} c_2, \quad c_1 = e^{-2\pi\mu} c_2 \Rightarrow$$

$$c_2 = e^{4\pi\mu} c_2 \Rightarrow (1 - e^{4\pi\mu}) c_2 = 0 \Rightarrow \text{either } c_2 = 0$$

$$\text{or } e^{4\pi\mu} = 1 \Rightarrow \mu = 0.$$

$\Downarrow$   
not the case

$\Downarrow$   
 $c_1 = 0$   
 $\Downarrow$   
 $y = 0$   
 $\Downarrow$   
not acceptable

So case (1) does not arise. (10)

$$(2) \quad \lambda = 0 \Rightarrow y'' = 0 \Rightarrow y = c_1 + c_2 x$$

$$\Rightarrow y' = c_2$$

$$0 = y'(-\pi) = c_2 \Rightarrow c_2 = 0 \Rightarrow y'(\pi) = 0 \quad \checkmark$$

So in this case  $y(x) = c_1$  when  $c_1 \in \mathbb{R} - \{0\}$ .  
This is an acceptable solution it corresponds to

$$\boxed{\lambda = 0} \quad (10)$$

$$(3) \quad \lambda \in \mathbb{R}^+ \Rightarrow \exists \mu \in \mathbb{R}^+, \lambda = \mu^2 \Rightarrow y'' + \mu^2 y = 0$$

$$\Rightarrow y = c_1 e^{i\mu x} + c_2 e^{-i\mu x}$$

$$\Rightarrow y' = i\mu (c_1 e^{i\mu x} - c_2 e^{-i\mu x})$$

$$0 = y'(-\pi) = i\mu (c_1 e^{-i\pi\mu} - c_2 e^{i\pi\mu}) \quad \mu \neq 0 \Rightarrow$$

$$0 = y'(\pi) = i\mu (c_1 e^{i\pi\mu} - c_2 e^{-i\pi\mu})$$

$$\Rightarrow c_1 = e^{2i\pi\mu} c_2, \quad c_1 = e^{-2i\pi\mu} c_2$$

$$\Rightarrow c_2 = e^{4i\pi\mu} c_2 \Rightarrow (1 - e^{4i\pi\mu}) c_2 = 0$$

$$c_2 = 0 \Rightarrow c_1 = 0 \Rightarrow y = 0 \Rightarrow \text{not acceptable.}$$

$$c_2 \neq 0 \Rightarrow e^{4i\pi\mu} = 1 \Rightarrow 4\pi\mu = 2\pi n$$

for some  $n \in \mathbb{Z}^+$

$$\Rightarrow \mu = \frac{n}{2} \text{ for } \boxed{\text{some } n \in \mathbb{Z}^+}$$

$$\Rightarrow \boxed{\lambda = \frac{n^2}{4}} \text{ \& } y(x) = c_2 (e^{2i\pi\mu} e^{i\mu x} + e^{-i\mu x})$$

$$\Rightarrow y(x) = c_2 \left( e^{in\pi} e^{\frac{inx}{2}} + e^{-\frac{inx}{2}} \right) = c_2 \left( (-1)^n e^{\frac{inx}{2}} + e^{-\frac{inx}{2}} \right)$$

$$= \underbrace{2(-1)^n c_2}_a \left[ \underbrace{e^{\frac{inx}{2}} + (-1)^n e^{-\frac{inx}{2}}}_b \right]$$

$$y(x) = \begin{cases} k_n \cos\left(\frac{nx}{2}\right) & \text{for } n: \text{ even} \\ ik_n \sin\left(\frac{nx}{2}\right) & \text{for } n: \text{ odd} \end{cases}$$

(10)

**Problem 2.** Find all stationary points of the function  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $f(x, y) = \sin(xy)$  and determine its local minimum, maximum, and saddle points. (30 points)

$$\vec{\nabla} f = 0$$

$$\frac{\partial f}{\partial x} = y \cos(xy), \quad \frac{\partial f}{\partial y} = x \cos(xy)$$

$$\frac{\partial f}{\partial x} = 0 \Rightarrow y \cos(xy) = 0 \quad (i)$$

$$\frac{\partial f}{\partial y} = 0 \Rightarrow x \cos(xy) = 0 \quad (ii)$$

Either (i)  $\boxed{x=0} \Rightarrow \cos(xy) = 1 \Rightarrow \boxed{y=0} \quad (5)$

(2)  $\boxed{x \neq 0} \Rightarrow \cos(xy) = 0 \Rightarrow xy = (2k+1)\frac{\pi}{2} \quad k \in \mathbb{Z}$

$$\Rightarrow \boxed{y = \frac{(2k+1)\pi}{2x}} \quad (5)$$

So the stationary points are those with coordinates:

$$(0, 0) \text{ and } \left(x, \frac{(2k+1)\pi}{2x}\right) \text{ with } x \in \mathbb{R} - \{0\}$$

$$f_{xx} = \frac{\partial^2 f}{\partial x^2} = -y^2 \sin(xy) \quad f_{xy} = \frac{\partial^2 f}{\partial x \partial y} = \cos(xy) - xy \sin(xy)$$

$$f_{yy} = \frac{\partial^2 f}{\partial y^2} = -x^2 \sin(xy)$$

$$H = \begin{pmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{pmatrix} \quad (5)$$

- At  $(0, 0)$ :  $\sin(xy) = 0, \cos(xy) = 1 \Rightarrow H = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad (5)$

$\Rightarrow \det H = -1 \Rightarrow$  Eigenvalues have opposite signs  $\Rightarrow (0, 0)$  is a saddle point (5)

- At  $\left(x, \frac{(2k+1)\pi}{2x}\right)$  with  $x \in \mathbb{R} - \{0\}$

$$\cos(xy) = 0, \quad \sin(xy) = (-1)^k, \quad xy = \frac{(2k+1)\pi}{2}$$

$$\Rightarrow H = \begin{pmatrix} -\frac{(2k+1)\pi^2 (-1)^k}{4x^2} & -\frac{(2k+1)\pi}{2} (-1)^k \\ -\frac{(2k+1)\pi}{2} (-1)^k & -x^2 (-1)^k \end{pmatrix}$$

$\Rightarrow \det H = 0 \Rightarrow$  One of the eigenvalues is zero. (5)

The 2nd derivative test is inconclusive. Looking closely into the 3rd order corrections to linear approximation of  $f$  shows that  $\left(x, \frac{(2k+1)\pi}{2x}\right)$  is neither min, max, nor a saddle point.

### 3rd Order corrections: (Not Expected in)

let  $a_k := \frac{(2k+1)\pi(-1)^k}{2}$

Quite

$$H = (-1)^{k+1} \begin{pmatrix} \frac{a_k^2}{x^2} & a_k \\ a_k & x^2 \end{pmatrix}$$

$$\det(H - hI) = \det \begin{bmatrix} (-1)^{k+1} \frac{a_k^2}{x^2} - h & (-1)^{k+1} a_k \\ (-1)^{k+1} a_k & (-1)^{k+1} x^2 - h \end{bmatrix}$$

$$= a_k^2 - (-1)^{k+1} x^2 h - (-1)^{k+1} \frac{a_k^2}{x^2} h + h^2 - a_k^2 = 0$$

$$\Rightarrow h \left[ h - (-1)^{k+1} \left( x^2 + \frac{a_k^2}{x^2} \right) \right] = 0$$

$$\Rightarrow h_1 = 0 \quad \& \quad h_2 = (-1)^{k+1} \left( x^2 + \frac{a_k^2}{x^2} \right)$$

$h = h_1 = 0$

$$H \vec{v}_i = \vec{0} \Rightarrow (-1)^{k+1} \begin{pmatrix} \frac{a_k^2}{x^2} & a_k \\ a_k & x^2 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \alpha = x^2 \gamma_i, \quad \beta = -a_k \gamma_i \quad \Rightarrow \quad \vec{v}_i = \gamma_i \begin{pmatrix} x^2 \\ -a_k \end{pmatrix}$$

Along  $\vec{v}_1$  direction:  $\Delta \vec{x} = \epsilon \begin{pmatrix} x^2 \\ -a_k \end{pmatrix} \quad \epsilon \in \mathbb{R}$

$$\sin[(x + \epsilon \Delta x)(y + \epsilon \Delta y)] = \sin(xy) + \vec{0} \cdot \vec{\nabla} f \cdot \Delta \vec{x} + \frac{1}{2} \Delta \vec{x} \cdot H \Delta \vec{x} + \dots$$

$$+ \frac{1}{6} \left( f_{xxx} (\Delta x)^3 + f_{yyy} (\Delta y)^3 + 3 f_{xxy} (\Delta x)^2 \Delta y + 3 f_{yyx} \Delta x (\Delta y)^2 + \dots \right)$$

$$f_{xxx} = -y^3 \csc(xy) = 0, \quad f_{yyy} = -x^3 \csc(xy) = 0$$

$$f_{xxy} = -[2y \sin(xy) + xy^2 \csc(xy)] = -2y(-1)^k = \frac{(2k+1)\pi(-1)^{k+1}}{2}$$

$$f_{yyx} = -[2x \sin(xy) + yx^2 \csc(xy)] = -2x(-1)^k = x(-1)^{k+1}$$

$$\sin[(x + \epsilon \Delta x)(y + \epsilon \Delta y)] = (-1)^k + \frac{\epsilon^3}{2} \left[ \frac{(2k+1)\pi(-1)^{k+1}}{x} \cdot x^4 \left( -\frac{(2k+1)\pi}{2} \right) + x(-1)^{k+1} \cdot \frac{(2k+1)^2 \pi^2}{4} \cdot x^2 \right] + \dots$$

$\Rightarrow$  Along  $\vec{v}_1$  direction

$$\sin[(x + \epsilon \Delta x)(y + \epsilon \Delta y)] = (-1)^k + \left( \frac{(-1)^k (2k+1) \pi x^2 \Delta x^2}{8} \right) \epsilon^3$$

This shows that along  $\vec{v}_1$ ,  $(x, y)$  is an inflection point along the normal direction  $\vec{v}_2$  it behaves as a min for  $k$ : odd & max for  $k$ : even.

So these points are neither min nor max. Strictly speaking there are not saddle points either.

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**Problem 3.** Let  $\vec{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  and  $R \subset \mathbb{R}^2$  be defined by

$$\vec{F}(x, y) := \begin{pmatrix} x \cosh y \\ x^2 \sinh y \end{pmatrix}, \quad R := \{(x, y) \in \mathbb{R}^2 \mid 0 \leq x \leq 1, 0 \leq y \leq x^2\}.$$

Sketch the boundary curve  $C$  of  $R$  and use Green's theorem in plane to evaluate  $\int_C \vec{F}(\vec{x}) \cdot d\vec{x}$  counterclockwise. (30 points)

$$I = \int_C \vec{F}(\vec{x}) \cdot d\vec{x} \stackrel{(5)}{=} \iint_R (\partial_1 F_2 - \partial_2 F_1) dx_1 dx_2$$

$$\partial_1 F_2 = \frac{\partial}{\partial x} (x^2 \sinh y) = 2x \sinh y$$

$$\partial_2 F_1 = \frac{\partial}{\partial y} (x \cosh y) = x \sinh y$$

$$\Rightarrow I = \int_0^1 dx \int_0^{x^2} dy [2x \sinh y - x \sinh y] \quad (5)$$

$$= \int_0^1 dx \int_0^{x^2} dy x \sinh y$$

$$= \int_0^1 dx \left( x \cosh y \Big|_0^{x^2} \right)$$

$$= \int_0^1 dx [x (\cosh(x^2) - 1)] \quad (5)$$

$$= \int_0^1 x \cosh(x^2) dx - \int_0^1 x dx$$

$u = x^2, \quad du = \frac{x}{2} dx$

$$= 2 \int_0^1 \cosh(u) du - \frac{x^2}{2} \Big|_0^1 \quad (5)$$

$$= 2 \sinh(u) \Big|_0^1 - \frac{1}{2} = 2 \sinh(1) - \frac{1}{2}$$

$$= e - e^{-1} - \frac{1}{2} \quad (5)$$

