

Newton's Method

Consider

$$g(x) = x - \Lambda f(x)$$

for some $\Lambda \in \mathbb{R}^{n \times n}$.Assuming Λ is invertible,

$$g(x_*) = x_* \iff$$

$$x_* - \Lambda f(x_*) = x_* \iff f(x_*) = 0$$

Choose Λ so that $J_g(x_*) = 0$, i.e.,

$$0 = J_g(x_*) = I_n - \Lambda J_f(x_*)$$

$$\iff (+) \Lambda = J_f(x_*)^{-1}$$

However, x_* is not known, so it is not practical to choose based on (+).~~Instead let us consider~~

~~$$g(x) = x - \Lambda(x) f(x)$$~~

 ~~$\Lambda(x) \in \mathbb{R}^{n \times n}$ but a function of $x \in \mathbb{R}^n$.~~~~Choose it so that $J_g(x_*) = 0$~~

Instead, let us consider

$$g(x) = x - J_f(x)^{-1} f(x)$$

Would like $J_g(x_*) = 0$.

Letting $\delta_{ij} = 1$, $\delta_{ij} = 0$ if $i \neq j$,

and $K(x) := J_f(x)^{-1}$

$$\begin{aligned} \frac{\partial g_i(x)}{\partial x_j} &= \frac{\partial x_i}{\partial x_j} - \frac{\partial ([K(x) f(x)]_i)}{\partial x_j} \\ &= \delta_{ij} - \sum_{r=1}^n \frac{\partial \{ [K(x)]_{ir} f_r(x) \}}{\partial x_j} \end{aligned}$$

$$\begin{aligned} &= \delta_{ij} - \sum_{r=1}^n \frac{\partial [K(x)]_{ir} f_r(x)}{\partial x_j} \\ &\quad - \sum_{r=1}^n [K(x)]_{ir} [J_f(x)]_{rj} \end{aligned}$$

$$\begin{aligned} \Rightarrow \frac{\partial g_i(x_*)}{\partial x_j} &= \delta_{ij} - \underbrace{\sum_{r=1}^n [K(x_*)]_{ir} [J_f(x_*)]_{rj}}_{\substack{\text{ith row of } K(x_*) \times \text{jth column of } J_f(x_*) \\ = \delta_{ij}}} \\ &= 0 \end{aligned}$$

for $j, i = 1, \dots, n$. Hence, $J_g(x_*) = 0$.

Newton sequence

$\{x^{(k)}\}$ such that

$$x^{(k+1)} = x^{(k)} - J_f(x^{(k)})^{-1} f(x^{(k)})$$

for a given $x^{(0)} \in \mathbb{R}^n$

In practice, we proceed from $x^{(k)}$ to $x^{(k+1)}$ as follows:

(1) Solve the linear system

$$-J_f(x^{(k)}) p^{(k)} = -f(x^{(k)})$$

for $p^{(k)}$. (That is $p^{(k)} = -J_f(x^{(k)})^{-1} f(x^{(k)})$)

$$(2) x^{(k+1)} = x^{(k)} + p^{(k)}$$

Ex

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad f(x) = \begin{bmatrix} x_1^2 + 3x_1x_2 + x_2^2 - 29/400 \\ x_1^2 - x_1x_2 + x_2^2 - 13/400 \end{bmatrix}$$

$$x^{(k)} = (1, 0)$$

$$-J_f(x) = \begin{bmatrix} 2x_1 + 3x_2 & 3x_1 + 2x_2 \\ 2x_1 - x_2 & 2x_2 - x_1 \end{bmatrix}$$

$$-J_f(1, 0) = \begin{bmatrix} 2 & 3 \\ 2 & -1 \end{bmatrix} \quad f(1, 0) = \begin{bmatrix} 371/400 \\ 387/400 \end{bmatrix}$$

$$x^{(k+1)} = (1, 0) + p^{(k)}$$

where $p^{(k)}$ is the solution of

$$\begin{bmatrix} 2 & 3 \\ 2 & -1 \end{bmatrix} p^{(k)} = \begin{bmatrix} -371/400 \\ -387/400 \end{bmatrix}$$

THM

Suppose $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is such that $\partial^2 f_i / \{\partial x_j \partial x_k\}$ are continuous for $k, j = 1, \dots, n$ and all x in an open neighborhood $N(x_*)$ of x_* , a root of f . Suppose also $J_f(x_*)$ is invertible.

(i) There exists $\bar{B}(x_*, \epsilon) \subset N(x_*)$ such that Newton sequence $\{x^{(k)}\}$ converges to x_* for all $x^{(0)} \in \bar{B}(x_*, \epsilon)$.

(ii) The ~~rate~~^{order} of convergence of $\{x^{(k)}\}$ to x_* is at least quadratic.

Proof

(i) As $J_f(x_*)$ is invertible, and due to continuity of $\partial f_i / \partial x_j$, the Jacobian $J_f(x)$ remains invertible in an open neighborhood $\tilde{N}(x_*) \subset N(x_*)$ of x_* .

Indeed, as $\partial^2 f_i / \partial x_j \partial x_k$ are also continuous, the entries of $J_f^{-1}(x)$ have continuous first derivatives in $\tilde{N}(x_*)$.

The entries of the Jacobian of $g(x) = x - J_f^{-1}(x) f(x)$ also have continuous first derivatives in $\tilde{N}(x_*)$ with $J_g(x_*) = 0$. Hence, the result follows (see the thm on page ② of [CH4-P2]) ~~where~~ ^{for some} $\bar{B}(x_*, \epsilon) \subset \tilde{N}(x_*)$.

(ii) Let $M := \max \{ \|J_f^{-1}(x)\|_\infty \mid x \in \bar{B}(x_*, \epsilon) \}$, γ be such that

$$\|J_f(x) - J_f(y)\|_\infty \leq \gamma \|x - y\|_\infty \quad \forall x, y \in \bar{B}(x_*, \epsilon)$$

(The existence of such a γ is due to continuity of $\frac{\partial^2 f_i}{\partial x_j \partial x_k}$.) (4)

By Taylor's thm with integral remainder,

$$0 = f(x_*) = f(x^{(k)}) + \int_0^1 \underline{J}_f(x^{(k)} + t(x_* - x^{(k)})) (x_* - x^{(k)}) dt$$

$$\Rightarrow 0 = \underbrace{\underline{J}_f(x^{(k)})^{-1} f(x^{(k)})}_{x^{(k)} - x^{(k+1)}} + (x_* - x^{(k)}) + \underline{J}_f(x^{(k)})^{-1} \int_0^1 \{ \underline{J}_f(x^{(k)} + t(x_* - x^{(k)})) - \underline{J}_f(x^{(k)}) \} (x_* - x^{(k)}) dt$$

$$\Rightarrow x^{(k+1)} - x_* = \underline{J}_f(x^{(k)})^{-1} \int_0^1 \{ \underline{J}_f(x^{(k)} + t(x_* - x^{(k)})) - \underline{J}_f(x^{(k)}) \} (x_* - x^{(k)}) dt$$

where we assume $x^{(k)} \in \bar{B}(x_*, \epsilon)$. Indeed, we can assume

(x) $\epsilon \leq \sqrt{2\epsilon/\gamma_M}$ as we can choose ϵ as small as we wish.

Taking the norms of both sides and employing the submultiplicative property

$$\begin{aligned} \text{(xx)} \quad \|x^{(k+1)} - x_*\|_\infty &\leq \|\underline{J}_f(x^{(k)})^{-1}\|_\infty \int_0^1 \underbrace{\|\underline{J}_f(x^{(k)} + t(x_* - x^{(k)})) - \underline{J}_f(x^{(k)})\|_\infty}_{\leq \pm \gamma \|x^{(k)} - x_*\|_\infty} \|x^{(k)} - x_*\|_\infty dt \\ &\leq \frac{\gamma M}{2} \|x^{(k)} - x_*\|_\infty^2 \end{aligned}$$

Now

$$\|x^{(k)} - x_*\|_\infty \leq \epsilon \Rightarrow \|x^{(k+1)} - x_*\|_\infty \leq \frac{\gamma M}{2} \epsilon^2 \stackrel{\text{due to (x)}}{\leq} \epsilon.$$

Hence, given $x^{(0)} \in \bar{B}(x_*, \epsilon)$, we have $x^{(k)} \in \bar{B}(x_*, \epsilon)$ for all k .

Assume also $\epsilon \leq 1/\gamma_M$. Let $\epsilon^{(k)} = \frac{1}{M} \left(\frac{1}{2}\right)^{2^{-k}}$, $M = \frac{\gamma M}{2}$.

Then

$$\begin{aligned} \|x^{(k)} - x_*\|_\infty \leq \epsilon^{(k)} &\stackrel{\text{using (xx)}}{\Rightarrow} \|x^{(k+1)} - x_*\|_\infty \leq M \left\{ \frac{1}{M} \left(\frac{1}{2}\right)^{2^{-k}} \right\}^2 \\ &= \frac{1}{M} \left(\frac{1}{2}\right)^{2^{-(k+1)}} = \epsilon^{(k+1)} \end{aligned}$$

as well as $\|x^{(0)} - x_*\|_\infty \leq \epsilon \leq \frac{1}{\gamma M} = \frac{1}{2M} = \epsilon^{(0)}$. By induction

$$\|x^{(k)} - x_*\|_\infty \leq \epsilon^{(k)} \quad \forall k, \quad \text{and} \quad \lim_{k \rightarrow \infty} \frac{\epsilon^{(k+1)}}{\{\epsilon^{(k)}\}^2} = M.$$

This yields an order of convergence at least two. \square

(5)

Variant of Newton's Method
that usually Converges Globally

$\{x^{(k)}\}$ - Newton sequence

Would like

$$(GB) \quad \lim_{k \rightarrow \infty} x^{(k)} = x_* \quad \text{s.t.} \quad f(x_*) = 0$$

for all $x^{(0)} \in \mathbb{R}^n$.

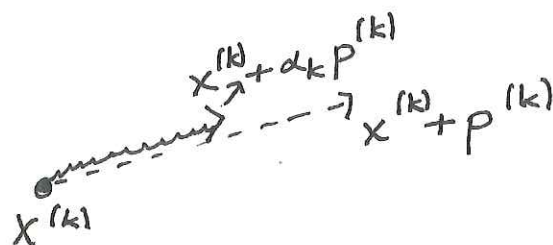
Line search techniques

$$x^{(k+1)} = x^{(k)} + \alpha_k p^{(k)}$$

$$p^{(k)} \quad \text{s.t.} \quad \nabla f(x^{(k)}) p^{(k)} = -f(x^{(k)})$$

$$\alpha_k \in (0, 1] \quad \text{step-length}$$

How shall we choose α_k ?



Define $r(\alpha) := \|f(x^{(k)} + \alpha p^{(k)})\|_2$ ($r: \mathbb{R} \rightarrow \mathbb{R}^*$)

$$r'(\alpha) = \frac{1}{2 \|f(x^{(k)} + \alpha p^{(k)})\|_2} 2 f(x^{(k)} + \alpha p^{(k)})^T \nabla f(x^{(k)} + \alpha p^{(k)}) p^{(k)}$$

$$r'(0) = \frac{f(x^{(k)})^T \left(-\underbrace{J_f(x^{(k)})}_{n \times n} p^{(k)} \right) - f(x^{(k)})}{\|f(x^{(k)})\|_2}$$

$$= \frac{-\|f(x^{(k)})\|_2^2}{\|f(x^{(k)})\|_2} = -\|f(x^{(k)})\|_2 < 0$$

Hence,

$r(\alpha) < r(0)$ for $\alpha > 0$ small enough

But would like more than a mere reduction, would like a sufficient reduction that guarantees (GB) usually.

Linear approximation of $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ at $x^{(k)}$

$$l(x) := \underbrace{f(x^{(k)})}_{n \times 1} + \underbrace{J_f(x^{(k)})}_{n \times n} \underbrace{(x - x^{(k)})}_{n \times 1}$$

Ex

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad f(x) = \begin{bmatrix} x_1^2 - 5x_1x_2 + 2x_2^2 - 3 \\ 3x_1^2 + x_1x_2 + x_2^2 + 1 \end{bmatrix}$$

linear approximation at $(0, 1)$

$$J_f(x) = \begin{bmatrix} 2x_1 - 5x_2 & -5x_1 + 4x_2 \\ 6x_1 + x_2 & x_1 + 2x_2 \end{bmatrix} \quad J_f(0, 1) = \begin{bmatrix} -5 & 4 \\ 1 & 2 \end{bmatrix}$$

$$f(0, 1) = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$l(x) = f(0, 1) + J_f(0, 1) \begin{pmatrix} x_1 \\ x_2 - 1 \end{pmatrix} \\ = \begin{bmatrix} -1 \\ 2 \end{bmatrix} + \begin{bmatrix} -5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 - 1 \end{bmatrix} = \begin{bmatrix} -5x_1 + 4x_2 - 5 \\ x_1 + 2x_2 \end{bmatrix}$$

Newton sequence in terms of linear approximations

$$x^{(k+1)} \text{ is s.t. } l(x^{(k+1)}) = 0$$

$$\text{where } l(x) = f(x^{(k)}) + \nabla f(x^{(k)}) (x - x^{(k)}).$$

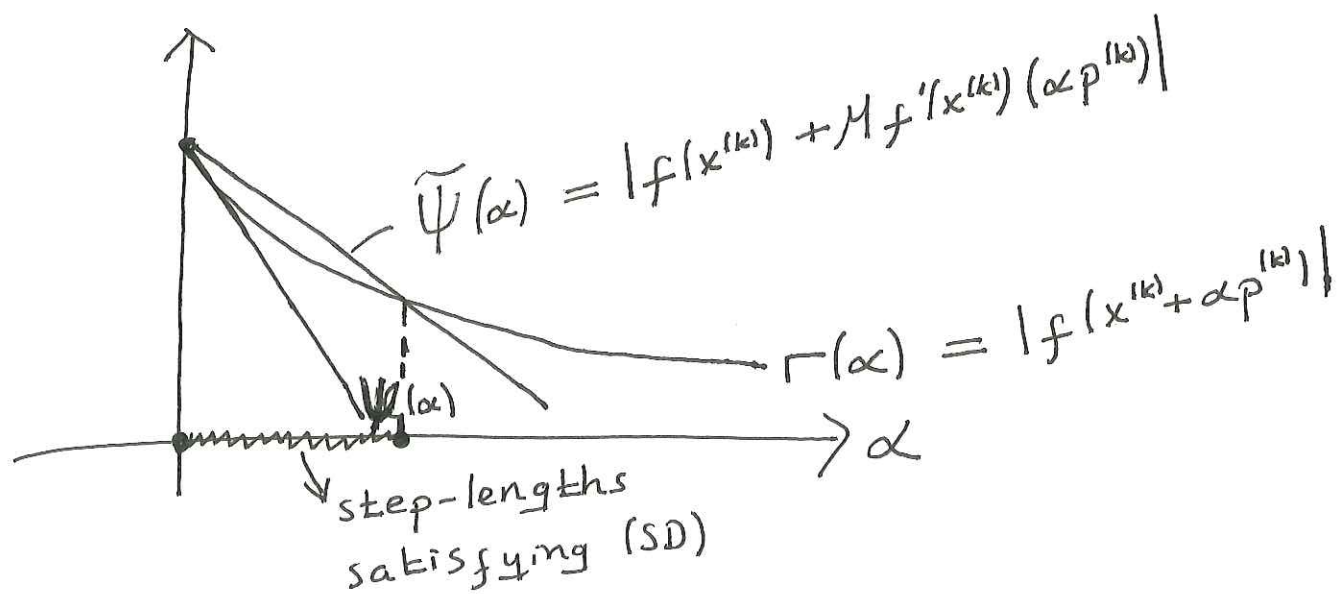
Sufficient reduction condition

$$(SD) \begin{cases} -r(\alpha) + r(0) \\ \geq \\ M(-\psi(\alpha) + \psi(0)) \end{cases}$$

for a given $M \in (0, 1)$, and

$$\psi(\alpha) := \|l(x^{(k)} + \alpha p^{(k)})\|_2$$

Illustration in the univariate case



Armijo backtracking line search
(given $x^{(k)}$ and $p^{(k)}$)

$$\alpha_k \leftarrow 1$$

while $\{(\tau(0) - \tau(\alpha)) < \mathcal{M}(\psi(0) - \psi(\alpha))\}$

$$\alpha_k \leftarrow \alpha_k / 2$$

end

return α_k

Remark

Guaranteed to terminate, because

$$\lim_{\alpha \rightarrow 0^+} \frac{\tau(0) - \tau(\alpha)}{\psi(0) - \psi(\alpha)} = 1$$

implying

$$\frac{\tau(0) - \tau(\alpha)}{\psi(0) - \psi(\alpha)} \geq \mathcal{M}$$

for all $\alpha > 0$ sufficiently close to 0.

Simplification of (SD)

$$\begin{aligned} & \|f(x^{(k)})\|_2 - \|f(x^{(k)} + \alpha p^{(k)})\|_2 \\ & \geq \mathcal{M} \left\{ \|f(x^{(k)})\|_2 - \|f(x^{(k)}) + \underbrace{f(x^{(k)}) p^{(k)} \alpha}_{-f(x^{(k)})}\|_2 \right\} \\ & = \alpha \mathcal{M} \|f(x^{(k)})\|_2 \end{aligned}$$

$$\Leftrightarrow \underbrace{(1 - \alpha \mathcal{M})}_{\in (0,1)} \|f(x^{(k)})\|_2 \geq \|f(x^{(k)} + \alpha p^{(k)})\|_2$$

Suppose α_k are chosen to satisfy (SD)
and $\alpha_k > \beta \quad \forall k$ for some $\beta > 0$.

$$\begin{aligned}\|f(x^{(k+1)})\|_2 &\leq \underbrace{(1 - \alpha_k M)}_{\leq (1 - \beta M) < 1} \|f(x^{(k)})\|_2 \\ &\leq (1 - \beta M)^{k+1} \|f(x^{(0)})\|_2\end{aligned}$$

so $\lim_{k \rightarrow \infty} \|f(x^{(k)})\|_2 = 0$.