KOÇ UNIVERSITY College of Sciences Quiz 5 Fall Semester 2013

Section 1

31 October 2013

Closed book. No calculators are to be used for this quiz. Quiz duration: 15 minutes

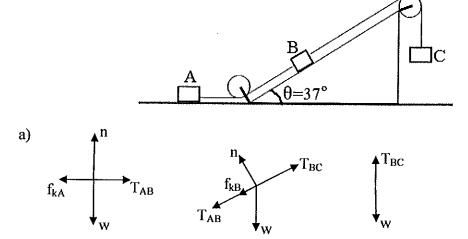
Name:

Student ID:

Signature:

Blocks A, B and C are connected by massless strings and pulleys are also massless and frictionless. (See the figure). Both blocks A and B have the same mass, $M_A = M_B = 2.5 kg$. The coefficient of kinetic friction between each block and surface is $\mu_k = 0.20$. Block C moves downward with constant speed.

- a) Draw three separate free-body diagrams showing all the forces acting on the blocks A, B and C.
- b) Calculate the tension in the string connecting blocks A and B.
- c) Calculate mass M_C of block C.



For mass A

For mass B

For mass C

- b) Since block C moves with constant speed, acceleration of all masses are zero. Therefore, $T_{AB}=f_{kA},\,f_{kA}=\mu_k m_A g=5N$.
- c) Since acceleration is zero, total force acting on the system is zero.

 $f_{kA}+f_{kB}+w_{l/B}=w_C$, where $w_{l/B}$ is the component of the weight of B parallel to the inclined plane.

 $f_{kB} = \mu_k m_A g \cos\theta = 4N$

 $W_{//B}=m_Bg\sin\theta=15N \implies W_C=24N \implies m_C=2.4kg$

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Section 2

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Name:

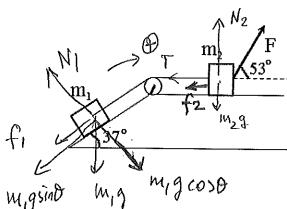
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Two blocks, $m_1 = 3.0 kg$ on the inclined plane ($\theta = 37^{\circ}$) and $m_2 = 5.0 kg$ on the horizontal plane are connected by light cord over a frictionless pulley. A force F=50N is acting on m_2 in a direction making 53^0 with the horizontal. Coefficient of static and kinetic frictions for both blocks and surfaces are $\mu_s = 0.3$ and $\mu_k = 0.2$. The system is

initially at rest. $(\cos 37^{\circ} = \sin 53^{\circ} = 0.8, \sin 37^{\circ} = \cos 53^{\circ} = 0.6, g = 10m/s^{2})$ a)If the system is released from rest, how does it behave? Explain briefly giving argument to support your answer.

b) Find the acceleration a of the blocks.



Summation of the forces acting in & direction ZF4= F coss3° = 50 (0.6) = 30 N Summation of the forces acting in @ direction IF = M, g sin37° +f15 + f25 = 18 + M5N, +M5N2 (3)(10)(0.6) + (0.3) (mg cos37°) + (0.3) (mg - Fsmss) JF = 18+7.2 +3 = 28.2 N/ Since ZF+ > ZF_ system starts to move in @ direction),) $a = \frac{5F_1 - 2F_2}{m_1 + m_2}$ System is moving we must use f_{1k} and $q = \frac{30 - 24.8}{8} = \frac{5.2}{8}$ $\sum_{F_1}^{F_2} = \frac{F_2 + F_3}{8 + (0.2)(24) + (0.2)(50 - 40)} = 24.8 \text{ N}$

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Section 3

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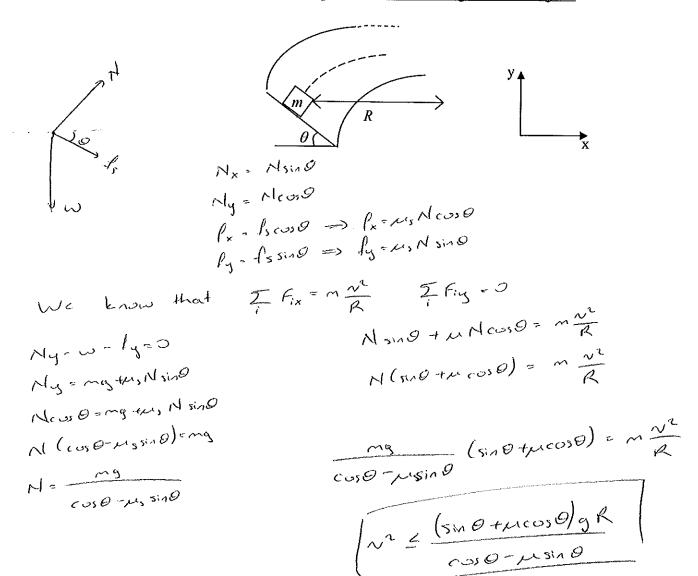
Name:

Student ID:

Signature:

A car rounds a banked curve (where the coefficient of static friction is μ) as shown in the figure. The radius of curvature of the road is R and the banking angle is θ .

What is the maximum speed the car can have before sliding up the banking (express your answer in terms of R, g, θ and μ). Draw the free body diagram for the car and write the equations of motion in each direction using the <u>coordinate axes given in the figure.</u>



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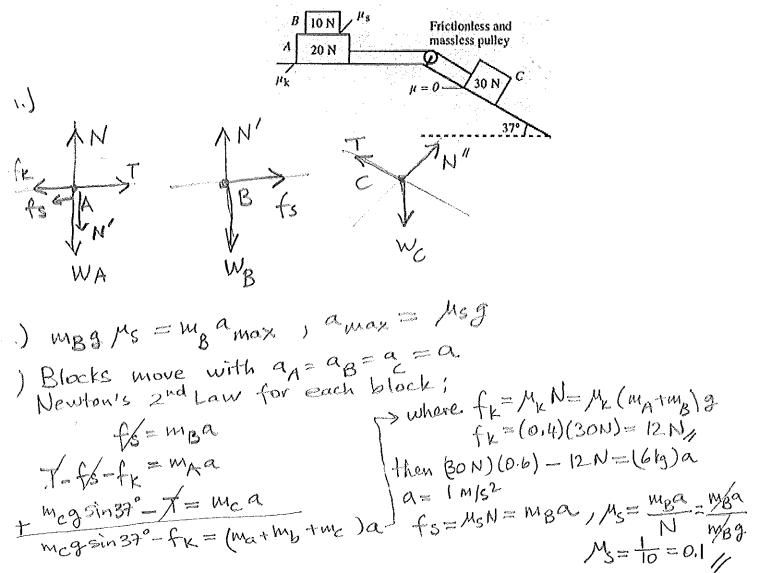
Section 4

Student ID:

Signature:

In the figure blocks A, B and C have weights of 20N, 10N and 30N, respectively. The coefficient of static friction between blocks A and B is μ_s and the coefficient of kinetic friction between block A and the horizontal surface is μ_k . There is no friction between block C and the inclined plane. The system of blocks are released from rest. We observe that blocks A and B move together ($g = 10m/s^2$; $\sin 37^o = 0.6$, $\cos 37^o = 0.8$) a)Draw free-body diagram for each block just after the release.

- b)In terms of g and μ_s , what is a, the maximum acceleration that block B can have without sliding over block A?
- c)If $\mu_k = 0.4$, what is the minimum μ_s between A and B so that B does not slip and they (A and B) move together?



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Section 5

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Name:

Student ID:

Signature:

A car rounds a banked curve (where the coefficient of static friction is μ) as shown in the figure .The radius of curvature of the road is R and the banking angle is θ .

What is the minimum speed the car can have before sliding down the banking (express your answer in terms of R, g, θ and μ). Draw the free body diagram for the car and write the equations of motion in each direction using the coordinate axes given in the figure.

