

Closed book. No calculators are to be used for this quiz.

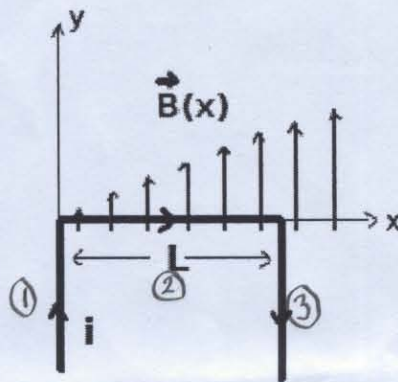
Quiz duration: 10 minutes

Name:

Student ID:

Signature:

Calculate the magnitude and direction of the force acting on the wire in the figure in terms of L , i , and the variable magnetic field $\vec{B}(x) = B_0(x/L)\hat{j}$.

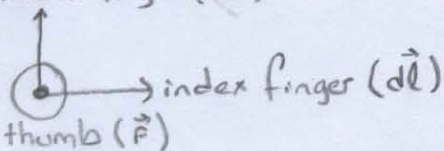


$$d\vec{F} = I d\vec{l} \times \vec{B}$$

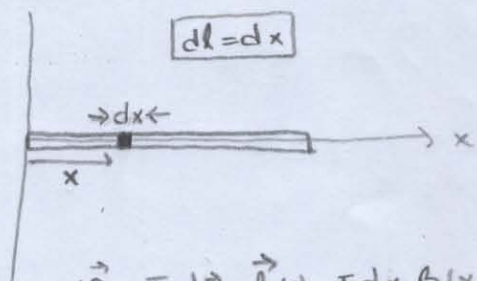
There is no force on side ① and ③, because $(d\vec{l} \times \vec{B} = 0)$ current and magnetic field lines are parallel.

The direction of \vec{F} on side ② can be found by right-hand-rule.

middle finger (\vec{B})



$$\vec{F} = \left(\frac{1}{2} I B_0 L\right) \hat{k}$$



$$d\vec{F} = I dx \hat{i} \times B(x) \hat{j} = I dx \cdot B(x) \sin 90^\circ \hat{k}$$

$$B(x) = B_0 \cdot \frac{x}{L}$$

$$dF = \frac{I B_0}{L} \cdot x dx$$

$$F = \int_0^L dF = \int_0^L \left(\frac{I B_0}{L}\right) x dx$$

$$F = \frac{I B_0}{L} \left[\frac{x^2}{2} \right]_{x=0}^{x=L} = \boxed{\frac{1}{2} I B_0 L = F}$$

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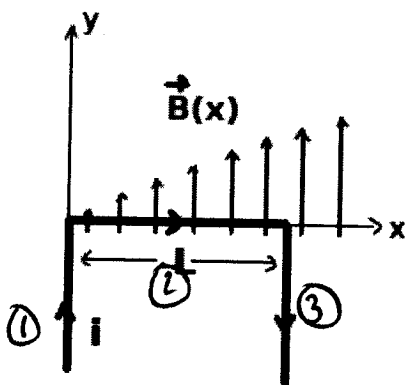
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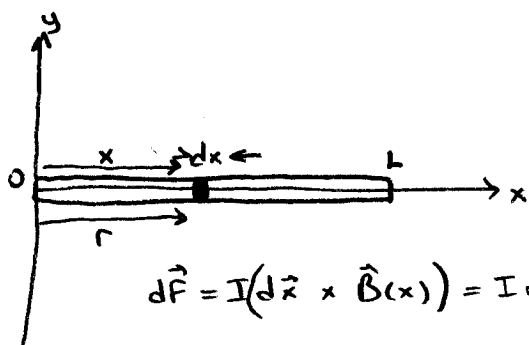
Signature:

Using $d\vec{\tau} = \vec{r} \times d\vec{F}$, calculate the magnitude and direction of the torque (with respect to the y-axis) acting on the wire in the figure in terms of L , i , and the variable magnetic field $\vec{B}(x) = B_0(x/L)\hat{j}$.



There is no force on side ① and ③, because current and magnetic field lines are parallel.

On side ②:



$$d\vec{F} = I(d\vec{x} \times \vec{B}(x)) = I dx B(x) \sin 90^\circ$$

$$B(x) = \frac{B_0 \cdot x}{L} \Rightarrow dF = \frac{IB_0}{L} \cdot x dx$$

$$d\vec{\tau} = \vec{r} \times d\vec{F}, (\vec{r} = x\hat{i})$$

$$= r dF \sin 90^\circ = x dF$$

$$d\tau = \frac{IB_0}{L} x^2 dx$$

$$\tau = \int_0^L d\tau = \frac{IB_0}{L} \int_0^L x^2 dx = \frac{IB_0}{L} \left(\frac{x^3}{3} \right) \Big|_{x=0}^{x=L}$$

$$\tau = \frac{1}{3} IB_0 L^2$$

The direction of \vec{F} on side ② is (\hat{x}) by right-hand-rule.

The direction of $\vec{\tau}$ is $(-\hat{y})$

middle finger (\vec{F})

index finger (\vec{r})



thumb ($\vec{\tau}$)

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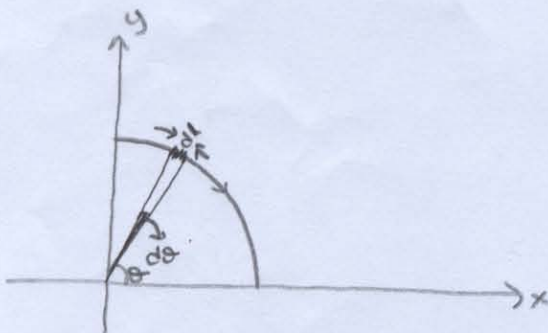
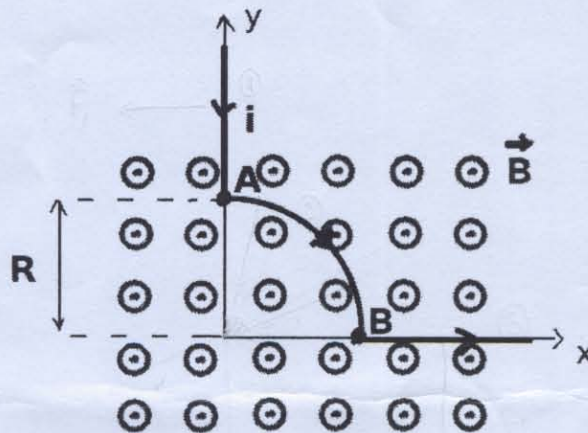
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Calculate the magnitude and the direction of the force acting on the circular portion A-B of the shown wire in terms of i , R , and the uniform magnetic field $\vec{B} = B\hat{k}$.



$$dl = R \cdot d\theta$$

$$d\vec{F} = I d\vec{l} \times \vec{B} = I \cdot dl \cdot B \cdot \sin 90^\circ$$

$$dF = I \cdot B \cdot R d\theta$$

$$d\vec{F} = -df_x - df_y$$

$$df_x = df \cos \theta$$

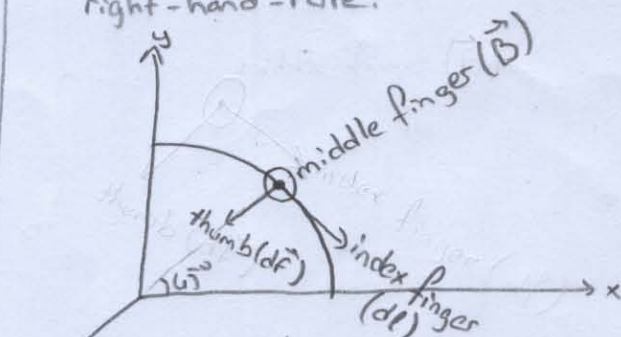
$$df_y = df \sin \theta$$

$$F_x = \int_0^{\pi/2} I B R \cos \theta d\theta = I B R$$

$$F_y = \int_0^{\pi/2} I B R \sin \theta d\theta = I B R$$

$$\vec{F} = F_x + F_y = -I B R \hat{i} - I B R \hat{j} = \vec{F}$$

The direction of $d\vec{F}$ can be found by right-hand-rule.



On the circular portion, $d\vec{F}$ always points to the origin, so by symmetry \vec{F} points to origin with an angle 45° .

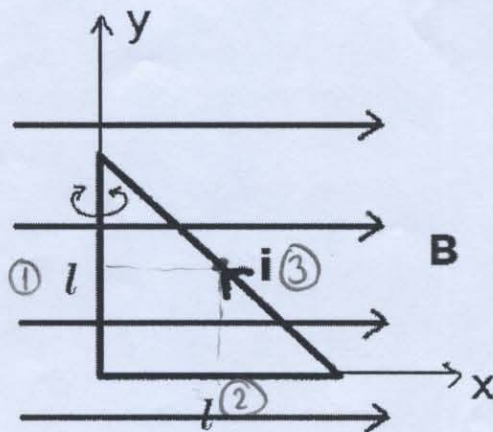
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The triangular current loop in the figure is attached to the y-axis and is free to rotate around it. Using $d\vec{\tau} = \vec{r} \times d\vec{F}$, calculate the magnitude and the direction of the net torque on the loop with respect to the y-axis in terms of B, i, and l.



No force on side ②
since $(d\vec{l} \parallel \vec{B})$

No torque on side ①
since side-1 is the rotation
axis.

On side ③:

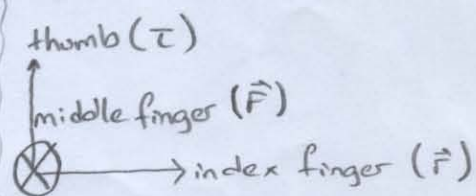
$$F_3 = i(l/\sqrt{2}) \cdot B \cdot \sin 45^\circ$$

$$\vec{F}_3 = -i l B \hat{y}$$

We can think that this force is applied on the
gravitational center of side-3.

$$\tau = \left(\frac{l}{2}\right) \cdot (i l B) \cdot \sin 90^\circ$$

$$\vec{\tau} = \frac{i B l^2}{2} \hat{y}$$



(Note: This solution would be incorrect if \vec{B} were nonuniform. See below)

More general solution:

$$d\vec{\tau} = \vec{r} \times d\vec{F} = r dF \sin 90^\circ = r dF$$

$$d\vec{F} = i d\vec{l} \times \vec{B} = i dl B \sin 45^\circ$$



$$dl = \sqrt{dx^2 + dy^2}$$

$$dx = dy$$

$$dl = dy\sqrt{2}$$

$$\vec{r} = y \hat{y}$$

$$d\tau = y \cdot dF = y \cdot i(dy\sqrt{2}) B \left(\frac{\sqrt{2}}{2}\right) = i B y dy$$

$$\tau = \int_0^l d\tau = i B \int_0^l y dy = \frac{i B l^2}{2}$$

$$\vec{\tau} = \frac{i B l^2}{2} \hat{y}$$

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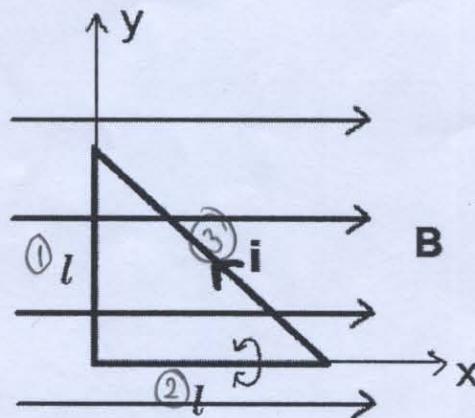
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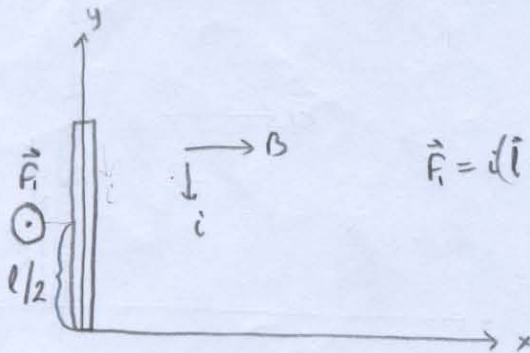
The triangular current loop in the figure is attached to the x-axis and is free to rotate around it. Using $d\vec{\tau} = \vec{r} \times d\vec{F}$, calculate the magnitude and the direction of the net torque on the loop with respect to the x-axis in terms of B, i, and l.



No torque on side ② since it is the rotation axis.

$$\tau_2 = 0$$

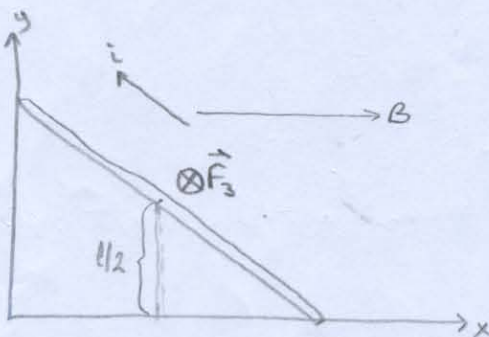
Since \vec{B} is uniform,



$$\vec{F}_1 = i(\vec{l} \times \vec{B}) = i l B \sin 90^\circ$$

$$\tau_1 = \frac{1}{2} \cdot F_1 \cdot \sin 90^\circ$$

$$\tau_1 = \frac{1}{2} i l^2 B$$



$$\vec{F}_3 = i(\vec{l} \times \vec{B}) = i l B \sin 45^\circ$$

$$\tau_3 = \frac{1}{2} \cdot F_3 \cdot \sin 90^\circ = \frac{1}{2} \cdot \left(i l B \frac{l}{2} \right)$$

$$\tau_3 = \frac{i l^2 B}{2}$$

$$\tau_{\text{net}} = \tau_1 - \tau_3 = 0$$

(Note: This method would not work if \vec{B} were nonuniform. See previous question)