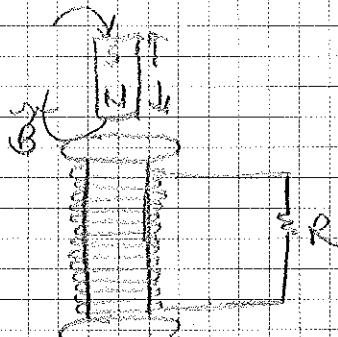


## Chapter 29. Electromagnetic Induction



Consider a coil and a magnet.

Experimental observation:

When the magnet is at rest where is no current flowing in the coil.

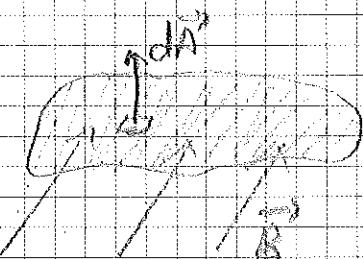
When the magnet is moved toward or away from the coil, current starts flowing in the coil.

Change in the magnetic field generates current. This is called the phenomenon of electromagnetic induction.

### Faraday's Law

Electromagnetic induction is governed by the Faraday's Law.

Consider a closed loop:



Faraday's Law states that a change in the magnetic flux flowing through the loop will generate an emf given as:

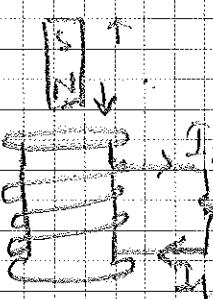
$$E_i = \frac{d\Phi}{dt}, \quad \Phi = B \cdot A$$

inside a source of emf  $E_i = \epsilon$

given by the Lenz's Law

$\epsilon$  is the induced emf.

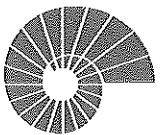
Induced emf ( $\epsilon$ ) has a specific direction. The direction is given by the Lenz's Law. Induction effect will generate a magnetic field which is opposite to the change in the total magnetic field.



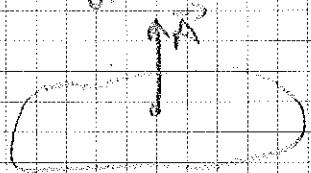
If the magnet is moved toward the coil, the coil will try to decrease the  $B$  field  $\Rightarrow$  flow direction is  $T_1$ .

Direction of  $E$  is the same as the direction of  $I$ .

If the magnet is moved away from the coil  $\Rightarrow$  flow direction is  $L_2$ .



Formally, we determine the direction of the induced current via currents



- Define a positive direction for the loop

- Determine the sign of induced emf.

(clockwise) if delta goes sign of E is negative  
(counter-clockwise) if sign of E is positive

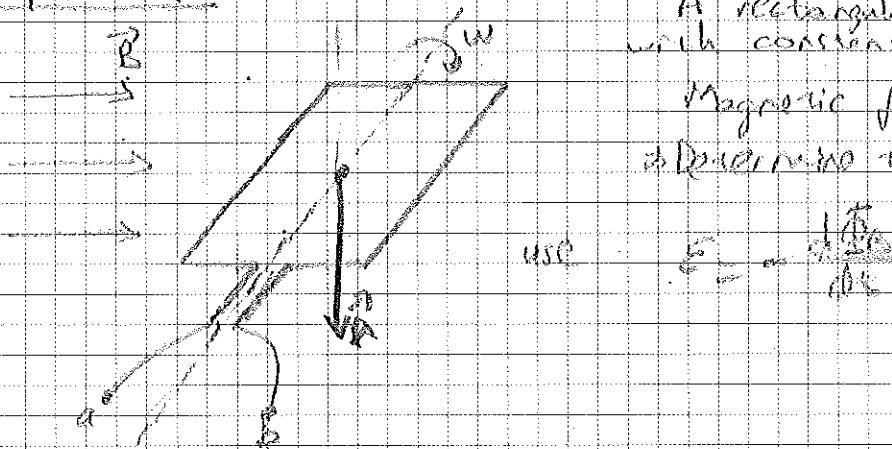
If delta goes sign of E is positive

Apply the right hand rule

- If the sign of induced emf is + your thumb should point in the direction of A

- If the sign of induced emf is - your thumb should point in the direction opposite to A.

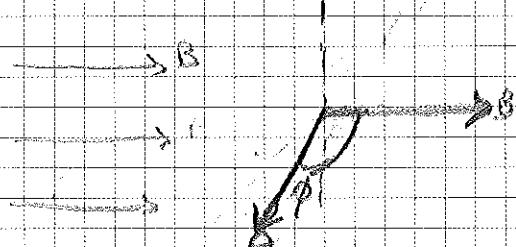
Example 29.4:



A rectangular loop is made to rotate with constant angular frequency  $\omega$ . Magnetic field  $B_0$  is uniform. Determining the induced emf

- Choose the direction of the vector A

At a certain time t:

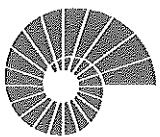


$$\Phi_B = \int B \cdot dA$$

$$\Phi_B = BA \cos \phi = BA \cos \theta$$

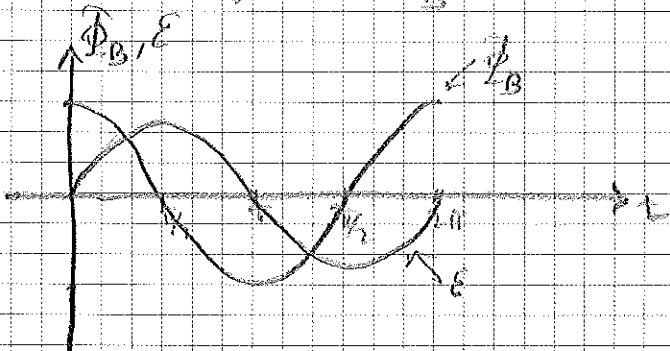
$$\text{and } w = \frac{d\theta}{dt} \Rightarrow d\Phi_B = BA \sin \theta \frac{d\theta}{dt} = BAw \sin \theta$$

$$\rightarrow \text{Induced emf: } E = \frac{d\Phi_B}{dt} = BAw \sin \theta = BAw \sin \omega t$$



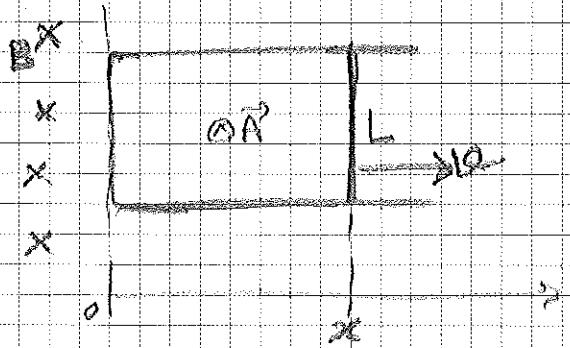
At  $\phi = 0$   $\Phi_B$  is maximum

for increasing  $\phi$   $\Phi_B$  decreases → direction of induced current



is from a to b

Example 2.3.6:



Consider a metal rod with length  $L$  across the two arms of a U-shaped conductor.

The rod is moved upwards right at a speed  $v$ .

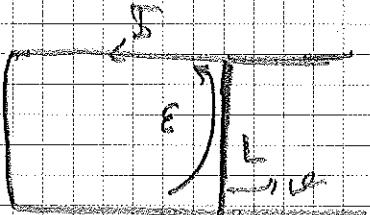
Magnitude and direction of the resulting emf.

Consider it is  $x$  in the direction (a)

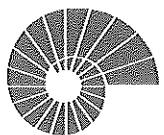
$$\rightarrow \Phi_B \text{ at time } t: \Phi_B(t) = BL(x(t))$$

$$\frac{d\Phi_B}{dt} = -BL \frac{dx}{dt} = BLv$$

The direction of  $E$ :



$E$  try to decrease the total flux.



Eks 29.3: Work and power in the slide wire generator



Work done by the force pulling the rod should be equal to the work of energy dissipation in the circuit.

$F_{ext}$ : force pulling the rod } since it is constant

$F_{IND}$ : magnetic forces }  $F_{ext} + F_{IND}$  no acceleration

Work done by  $F_{ext}$ :

$$\frac{d(F_{ext} \Delta x)}{dt} + F_{IND} \frac{dx}{dt}; F_{ext} \Delta x = I L B \Delta x$$

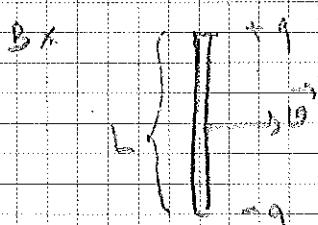
Power of energy dissipated in the circuit:

$$EI = BLvI$$

i. Mechanical energy is converted into electrical energy.

## 29.4 Motional Electromotive Force

Consider a ~~conductor~~ rod moving with a constant velocity under a constant magnetic field.



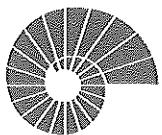
A charge element  $q$  will be subjected

to a magnetic force

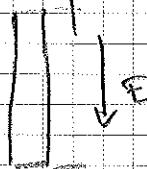
$$F_M = qvB$$

$\Rightarrow$  Positive charges will be collected on one side and negative charges on the other side.

At equilibrium there will be no net charge flow in the conducting rod.



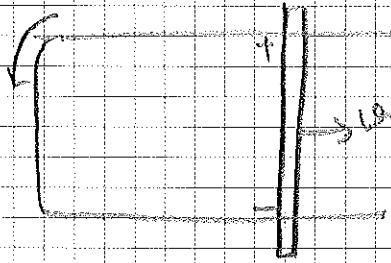
$$\vec{F}_e = q\vec{v} \times \vec{B} \Rightarrow q\vec{v} \cdot q\vec{v} B \Rightarrow \boxed{\vec{E} = \vec{v} \times \vec{B}}$$



Potential difference on the road

$$\checkmark \quad \vec{E} L = \vec{v} B l$$

$\therefore \boxed{E = v B l}$  is called the motional emf.



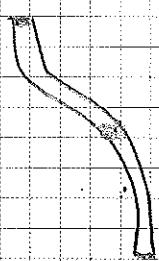
$E = v B l$  motional emf )  
or Faraday's Law

$$E = -\frac{d\Phi}{dt} = -v B l$$

They explain  
the same  
physical  
phenomenon.

In problems with moving conductors, motional emf can be applied rather than the Faraday's Law.

For a non straight conductor

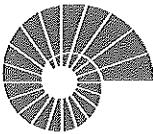


Assume a portion of the conductor with length  $dL$ . On this portion:

$$dE = \vec{E} dL \Rightarrow q \vec{v} \times \vec{B} = q \vec{v} \times \vec{B}$$

$$dE = (\vec{v} \times \vec{B}) \cdot dL$$

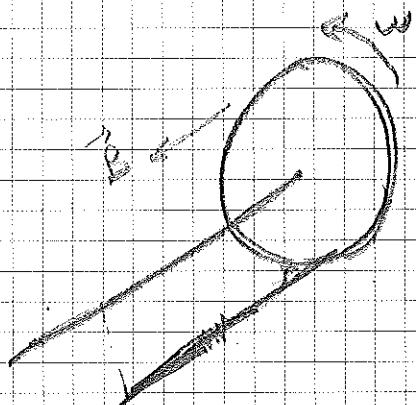
$$\Rightarrow \text{On the whole conductor } \boxed{E = \int dE = \int (\vec{v} \times \vec{B}) \cdot dL}$$



a) Haniz idezer generator

(17)

Example 29.11: Faraday Disk dynamo.



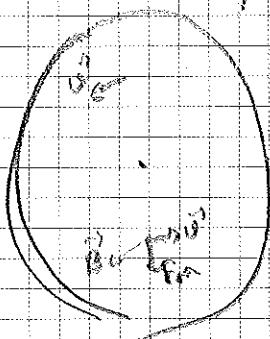
Consider a conducting disk with radius  $R$ , rotating with angular velocity  $\omega$  about its axis going through the center in the normal direction.

The disk is subject to a constant magnetic field  $B$ .

Induced emf between the center and the rim of the disk?

Consider a charge  $q$  on the disk. This charge will move with velocity  $v$  in the tangential direction.

as Magnetic force  $F_m = qv \times B$  is in the radial direction.



→ At equilibrium a positive potential difference will be built up between the rim and the center.  
Such that charges flowing in the circuit do not accelerate in the radial direction.

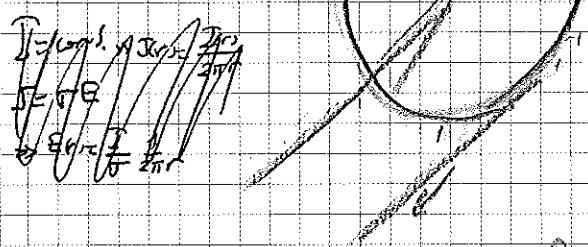
$$F_m = qv \times B = qE \Rightarrow E = vB$$

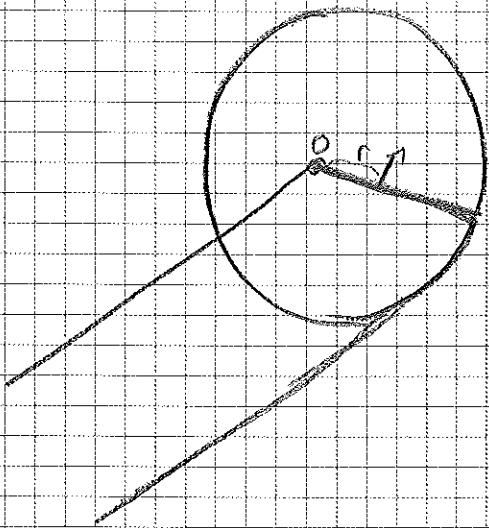
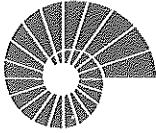
$$E(r) = B\omega(r) = B\omega r$$

↑  
speed

at different  
radial location

$$\Rightarrow E = \int_{0}^{R} E(r) dr = \int B\omega r dr = \frac{1}{2} \omega B R^2 / \text{radial emf}$$



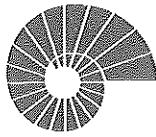


$$\oint \mathbf{B} \cdot d\mathbf{l} = \int (\mathbf{v} \times \mathbf{B}) \cdot d\mathbf{l}$$

$$\vec{v}(r) = r\omega \hat{\phi}, \quad \vec{B} = B \hat{e}_r, \quad d\vec{l} = dr \hat{\phi}$$

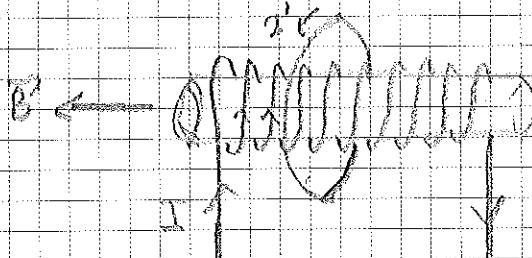
$$\Rightarrow \vec{v} \times \vec{B} = r\omega B \hat{e}_\theta$$

$$\oint \mathbf{B} \cdot d\mathbf{l} = \int_0^R r\omega B dr = \frac{1}{2} \omega B R^2 //$$



## 2.5 Induced Electric Fields:

Consider a solenoid and a wire loop.



If the current in the solenoid changes with time, an emf will be induced in the wire loop.

$$B = \mu_0 n I, \text{ (using Ampere's law)}$$

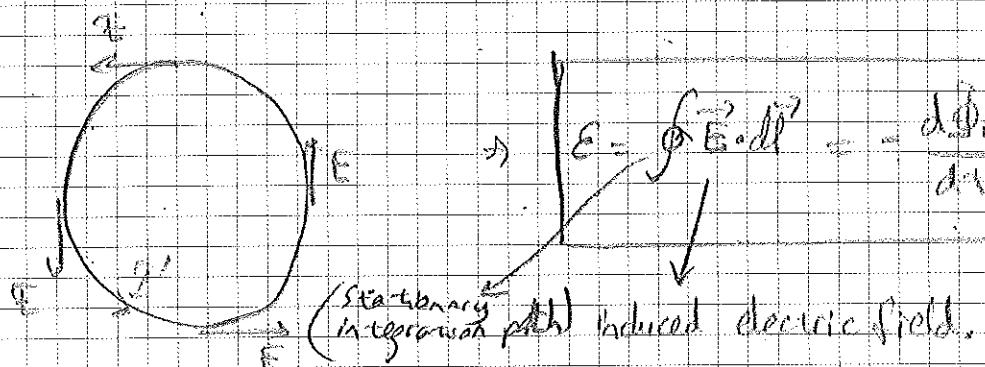
Then through the wire loop:  $\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I A$

$$\Rightarrow E = -\frac{d\Phi_B}{dt} = -\mu_0 n A \frac{dI}{dt}$$

If the loop has a total resistance  $R$ , the induced current in the loop is:

$$I = \frac{\mu_0 n A}{R} \frac{dI}{dt}, \text{ in magnitude.}$$

Direction is given by Lenz's law.

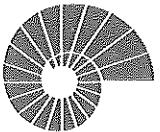


Even if the conductor is not moving in a uniform field, induced electric field can be obtained.

When a charge  $q$  goes once around the loop the total work done on it is  $qV$ .  $\Rightarrow$  The electric field in the loop is not conservative.

Normally,

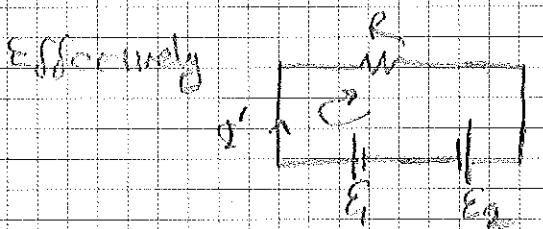
$$\int \mathbf{B} \cdot d\mathbf{l} = 0 \Rightarrow E = 0$$



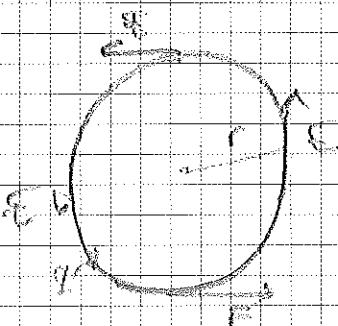
In the case of induction



$$\oint \vec{E} \cdot d\vec{l} = E_1 - IR = \frac{d\Phi_B}{dt} = \frac{\mu_0 A}{R} \frac{dI}{dt}$$



Consider the simple situation of a circular wire loop.



$$\begin{aligned}\oint \vec{E} \cdot d\vec{l} &= E 2\pi R = \frac{d\Phi_B}{dt} \\ \Rightarrow E &= \frac{1}{2\pi R} \frac{d\Phi_B}{dt}\end{aligned}$$

## 2.9.7 Displacement Current and Maxwell's Equations:

$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} (\oint \vec{B} \cdot d\vec{l}) \rightarrow$  Varying magnetic field generates electric fields

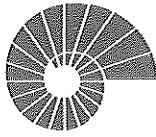
$\rightarrow$  Would varying electric field generate magnetic field?

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{total}}, \text{ Ampere's Law}$$

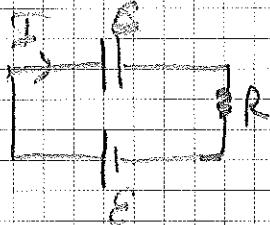
To this statement magnetic field generation is not governed by the electric field.

Indeed Ampere's law is incomplete!

Varying electric field also generates magnetic field.



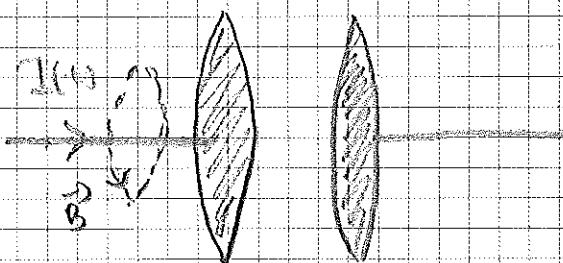
This is most obvious in the case of charging of a capacitor.



Consider this circuit and the capacitor is initially uncharged.

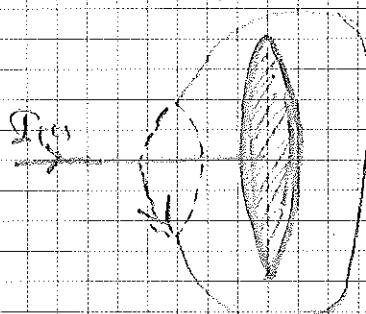
At a time  $t_1$ ,

Parallel plate capacitor,



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{loop}} + \mu_0 \Delta \Phi \text{ for the plane surface area.}$$

Now consider the same loop over a surface encompassing the first plate of the capacitor.



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \frac{\partial \Phi}{\partial t} = 0$$

But we know

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \Delta \Phi$$

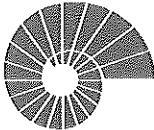
∴ There is a missing term.

Considering uniform electric field between the parallel plates:

$$\frac{d\Phi}{dt} = \frac{d(CV)}{dt} = C \frac{d(EA)}{dt} = C \frac{d}{dt} \left( \frac{1}{2} EA^2 \right)$$

$$\therefore \frac{d\Phi}{dt} = \frac{C}{2} \frac{dE}{dt} A^2 = \frac{C}{2} \frac{dE}{dt} \cdot EA$$

∴ If we write  $\oint \vec{B} \cdot d\vec{l} = \mu_0 \frac{d\Phi}{dt} + \mu_0 \frac{d\Phi}{dt}$ , the Ampere's law is valid for both conduction current and displacement current.

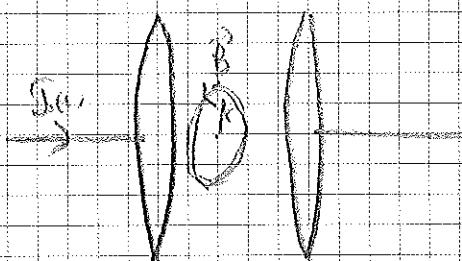


This equation is indeed valid for all situations!

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{ext} + \mu_0 \int_A \vec{J} \cdot d\vec{A}$$

$\int_A \vec{J} \cdot d\vec{A} = J_0 \frac{dA}{dt} = J_0 A \int \vec{v} \cdot d\vec{A}$  is called displacement current

Consider the measurement of  $B$  between the parallel plates:



If the plates are circular,  $B$  at a distance  $r$  from the center is constant in magnitude and tangential in direction.

$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = B \cdot 2\pi r \cdot I_0 + \mu_0 \int_A \vec{v} \cdot d\vec{A}$$

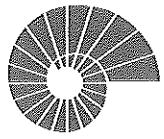
$$B 2\pi r = 0 + \mu_0 \int_A \vec{v} \cdot d\vec{A} = \mu_0 A \frac{d\vec{v}}{dt}$$

If the loop covers the whole area:

$$I_D = I_0 \pi r^2 = I(t)$$

$$\therefore I_D(t) = \frac{I(t)}{r} A(t) = \frac{I(t)}{R} \pi r^2 = \frac{\mu_0 r^2}{R} I(t)$$

$$\Rightarrow B = \frac{1}{2\pi r} \frac{\mu_0 r^2}{R} I(t) = \boxed{\frac{\mu_0}{2\pi R} I(t)}$$



## Maxwell's Equations of Electromagnetism

Now we can write down all the relationships between the electric field with the magnetic field:

$$\text{Modified Ampere's Law: } \oint \vec{B} \cdot d\vec{l} = \mu_0 (I_C + \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{A})$$

$$\text{Faraday's Law: } \oint \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{A}$$

$$\text{Gauss' Law: } \int \vec{E} \cdot d\vec{A} = \frac{\text{Dens.}}{\epsilon_0}$$

(for electric field)

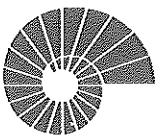
$$\text{Gauss' law for magnetic field: } \int \vec{B} \cdot d\vec{A} = 0 \quad \text{No magnetic monopoles}$$

All the basic relations between fields and their sources are contained in Maxwell's equations.

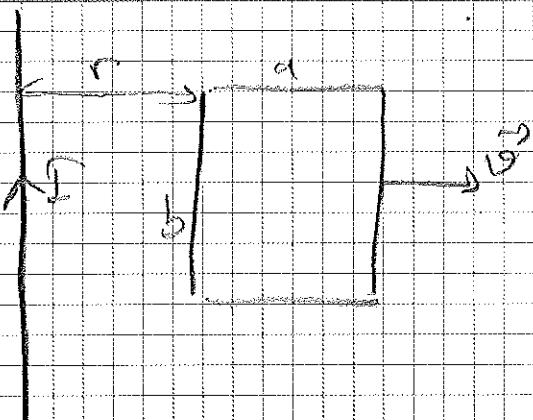
Maxwell's Equations together with the Equation of the Lorentz Force

$$\vec{F} = q (\vec{E} + \vec{v} \times \vec{B})$$

constitute all the fundamental relations of Electromagnetism.



29.49)



The loop is being pulled to the right at constant speed  $v$ . Magnitude and direction of the induced emf.

$$\Phi_B = \int B_s \cdot d\vec{a} = \int \frac{\mu_0 I}{2\pi r} dr dy = \frac{\mu_0 I}{2\pi} L \int \frac{dr}{r}$$

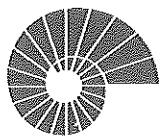
$$\therefore \frac{\mu_0 I L}{2\pi} \ln\left(\frac{r+a}{a}\right)$$

$$\frac{d\Phi_B}{dt} = \frac{\mu_0 I L}{2\pi} \left( \frac{1}{r+a} \right) \left( -\frac{v(r+a)}{r^2} \right) \frac{dr}{dt}$$

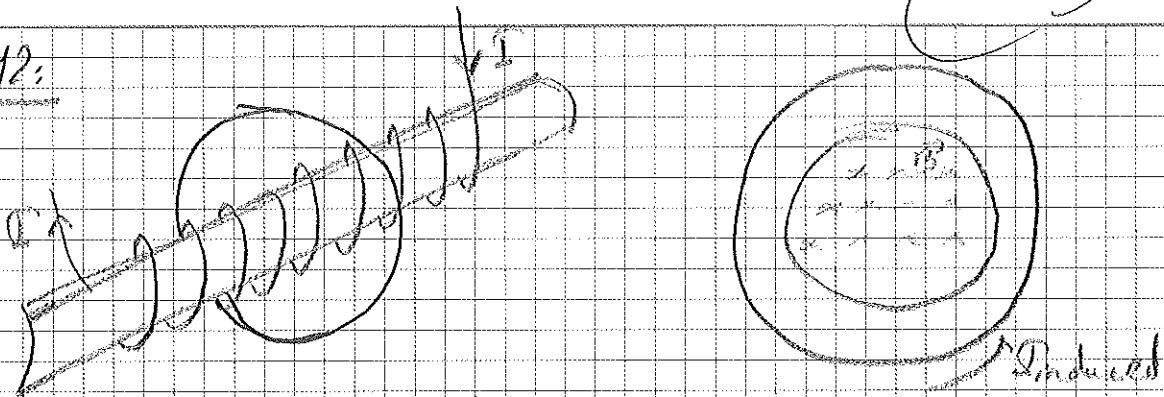
$$\frac{\mu_0 I L}{2\pi} \frac{v}{r+a} \frac{-a}{r^2} \frac{dr}{dt} = -\frac{\mu_0 I L}{2\pi} \frac{a}{r(r+a)} \frac{v}{\cancel{r}}$$

$$\therefore E = \frac{d\Phi_B}{dt} = \frac{\mu_0 I L}{2\pi} \frac{a}{r(r+a)} \frac{v}{\cancel{r}}$$

Direction  $\rightarrow$  clockwise.



EN 23.12:



Suppose a long solenoid is wound with 500 turns/meter, and the current in the windings is increasing at the rate of  $100\text{ A/s}$ .

(a) Cross-sectional area of the solenoid is  $4 \times 10^{-4}\text{ m}^2$ .

a) Magnitude of the induced emf in the wire loop outside the solenoid.

b) Magnitude of the induced electric field if the wire loop has a radius of 2 cm

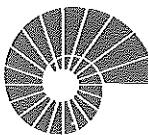
$$a) E = -\frac{d\Phi_B}{dt}, \Phi_B = BA = \mu_0 I n A$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{ext}} \quad B = \mu_0 I n \quad B = \mu_0 I n / 2\pi r$$

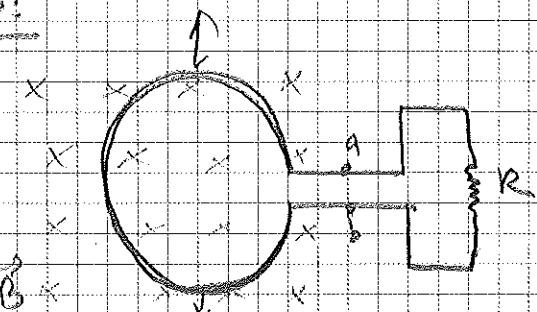
$$\Rightarrow E = -\mu_0 n A \frac{d\Phi_B}{dt} = -\mu_0 n A \frac{d}{dt} \left( B A \right) = -\mu_0 n A \frac{d}{dt} \left( \mu_0 I n A \right) = -\mu_0^2 n^2 A^2 \frac{dI}{dt} = -\mu_0^2 n^2 A^2 \cdot 500 \cdot 4 \times 10^{-4} \cdot 100 = -25 \text{ V}$$

b)  $E = \oint \vec{E} \cdot d\vec{l} = 2\pi r E$ , due to symmetry

$$\Rightarrow E = \frac{E}{2\pi r} = \frac{25 \times 10^{-6}}{2\pi \times 2 \times 10^{-2}} = 2 \times 10^{-4} \text{ V/m}$$



Prob 29. 53:



A flexible circular loop of diameter 6.5 cm lies in a B-field of 0.95 T.

The loop is pulled forming a loop of zero area in 0.25 s.

a) Average induced emf in the circuit?

b) Direction of current in R?

$$\text{a) } \mathcal{E} = -\frac{d\Phi_B}{dt} \Rightarrow \mathcal{E}_{\text{avg}} = \frac{\Delta \Phi_B}{\Delta t} = \frac{(0 - (0.95) \pi \frac{(6.5 \times 10^{-2})^2}{4})}{0.25}$$
$$= 0.0126 \text{ V}$$

b) From a to b.